# Barodesy - A new perspective of hypoplasticity Aussois September 2014

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#### Division of Geotechnical and Tunnel Engineering University of Innsbruck

Aussois, September 2014

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## Embarcation pour Barodesie



#### The exotic island of Barodesy



Image: Image:



You don't need to take with you

- yield surface
- plastic potential
- normality rule
- . . .

# Empirical basis of barodesy: Experiments by Goldscheider



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## Empirical basis of barodesy: Experiments by Goldscheider



#### Versuche von Goldscheider<sup>1</sup> True triaxial tests



<sup>1</sup>M. Goldscheider. Grenzbedingung und Fließregel von Sand. Mechanics Research Communications, 3:463-468, 1976

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Prop. strain paths (P $\varepsilon$ P):  $\varepsilon_1 : \varepsilon_2 : \varepsilon_3 = \text{const.}$ Prop. stress paths (P $\sigma$ P):  $\sigma_1 : \sigma_2 : \sigma_3 = \text{const.}$ 

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- volume -preserving ('isochoric' or 'undrained'), tr**D**=0
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How depends **R** on the direction  $D^0(=D/|D|)$  of the corresponding proportional strain path?

How can we determine the relation  $\mathbf{R}(\mathbf{D}^0)$ ?

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With  $\sigma_i = \mu R_i(\mathbf{D}) = \mu R(D_i)$ 

we obtain:

 $R(D_1)R(D_2)R(D_3) < 0$  for  $tr \mathbf{D} = D_1 + D_2 + D_3 < 0$  (1)

 $\rightarrow$   $R(D_1)R(D_2)R(D_3)$  is function of  $D_1 + D_2 + D_3$ 

Recall:  $f(x_1)f(x_2) = f(x_1 + x_2) \rightsquigarrow f(x) = \exp(ax)$ 

→ exponential mapping:

$$\mathsf{R}(\mathsf{D}) = -\exp(a\mathsf{D}^0)$$

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#### Equation (2) maps consolidations into a cone with appex at $\mathbf{T} = \mathbf{0}$

Its boundary (corresponds to paths with tr D = 0): critical state surface

The intersection of the **R**-cone with a plane trT = const can be derived from equation (2):

For isochoric deformations  $(tr \mathbf{D}^0 = 0)$  we eliminate  $\mathbf{D}^0$  from (2):

$$\mathbf{D}^0 = \frac{1}{a} \ln(-\mathbf{R}) \ . \tag{3}$$

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 $\begin{aligned} \mathrm{tr} \mathbf{D}^0 &= \mathbf{0} \rightsquigarrow \quad \ln(-R_1R_2R_3) = \mathbf{0} \text{ or } R_1R_2R_3 = -1. \\ |\mathbf{D}^0| &= 1 \quad \rightsquigarrow \ (\ln R_1)^2 + (\ln R_2)^2 + (\ln R_3)^2 = a^2 \\ \end{aligned}$  For PP holds:  $\mathbf{T} = \mu \mathbf{R}, \ \mathbf{0} < \mu < \infty, \ \rightsquigarrow \mathbf{R} = \mathbf{T}/\mu^{-1} \end{aligned}$ 

$$\left(\ln\frac{T_1}{\sqrt[3]{T_1T_2T_3}}\right)^2 + \left(\ln\frac{T_2}{\sqrt[3]{T_1T_2T_3}}\right)^2 + \left(\ln\frac{T_3}{\sqrt[3]{T_1T_2T_3}}\right)^2 = a^2.$$
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Equation (4) is homogeneous of the zero-th degree in **T** ···· conical surface in *σ*-space with apex at **T** = **0**.

Its intersection with a plane trT =const practically coincides with the curve obtained by MATSUOKA & NAKAI:

$$\frac{(T_1 + T_2 + T_3)(T_1T_2 + T_1T_3 + T_2T_3)}{T_1T_2T_3} = \text{const} .$$
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$$\mathbf{T} = \mu \mathbf{R}, \ 0 < \mu < \infty, \ \rightsquigarrow \mathbf{R} = \mathbf{T}/\mu^{-1}$$

$$\left(\ln\frac{T_1}{\sqrt[3]{T_1T_2T_3}}\right)^2 + \left(\ln\frac{T_2}{\sqrt[3]{T_1T_2T_3}}\right)^2 + \left(\ln\frac{T_3}{\sqrt[3]{T_1T_2T_3}}\right)^2 = a^2.$$
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Equation (4) is homogeneous of the zero-th degree in  $\mathbf{T} \rightsquigarrow \text{conical}$  surface in  $\sigma$ -space with apex at  $\mathbf{T} = \mathbf{0}$ .

Its intersection with a plane trT =const practically coincides with the curve obtained by MATSUOKA & NAKAI:

$$\frac{(T_1 + T_2 + T_3)(T_1T_2 + T_1T_3 + T_2T_3)}{T_1T_2T_3} = \text{const} .$$
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$${}^{1}T_{1}T_{2}T_{3} = -1/\mu^{3} \rightsquigarrow \mu = -1/\sqrt[3]{T_{1}T_{2}T_{3}}.$$

$$\operatorname{tr} \mathbf{D}^{0} = 0 \rightsquigarrow \quad \ln(-R_{1}R_{2}R_{3}) = 0 \text{ or } R_{1}R_{2}R_{3} = -1.$$
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Cross section of the  $\mathbf{R}$ -cone with a deviatoric plane. Numerically obtained with equ. (2).

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#### Equation (2) can be calibrated if we know $\phi_c$ :

$${\it K}_c:=rac{1-\sinarphi_c}{1+\sinarphi_c}\;.$$

Evaluating the relation  $R_2/R_1 = K_c$  with equ. (2)  $\rightsquigarrow$ :

$$a = \sqrt{\frac{2}{3}} \ln K_c \tag{6}$$

Better simulations can be obtained with  $a := c_1 \exp(c_2 \epsilon)$  and  $c_1 = \sqrt{\frac{2}{3}} \ln K_c$ . This modification does not affect undrained proportional strain paths

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Rule 2 states that if we start from  $\mathbf{T} \neq \mathbf{0}$  and apply a constant  $\mathbf{D}$ , the stress will asymptotically approach the line  $\mathbf{T} = \mu \ \mathbf{R}^{0}$ :



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#### Thus, $\dot{\mathbf{T}}$ will fulfil the equation $\mathbf{T} + \dot{\mathbf{T}} \Delta t = \mu \mathbf{R}^0$ .

This equation can also be written as

$$\dot{\mathbf{T}} = \hat{f} \mathbf{R}^0 + \hat{g} \mathbf{T} . \tag{8}$$

To preserve homogeneity of the 1st degree with respect to  $\mathbf{D}$ ,  $\hat{f}$  and  $\hat{g}$  must be homogeneous of the 1st degree with respect to  $\mathbf{D}$ .

It proves that

$$\hat{f} := f \cdot \dot{\varepsilon} \cdot h(\sigma) \hat{g} := g \cdot \dot{\varepsilon} \cdot h(\sigma) / \sigma$$

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It contains a stress-dilatancy relation for peak states.

A simple way to fulfill equation (12) for limit states is to set

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#### For consolidations: $\mathbf{T}^0 = \mathbf{R}^0$ . Hence, equation (9) $\rightsquigarrow$

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For proportional paths:  $\dot{\mathbf{T}} = \dot{\sigma} \mathbf{T}^0$ , hence equation (9) reduces to

$$\dot{\sigma} = h \left( f + g \right) \dot{\varepsilon} \quad , \tag{15}$$

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Prof. Dimitrios Kolymbas, Universität Innsbruck Barodesy - A new perspective of hypoplasticity

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#### Equation (18) expresses compressibility at consolidations.

*h* expresses the stress-dependence of stiffness.

Stiffness increases with  $\sigma$  but should not vanish for  $\sigma = 0$ .

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e<sub>min</sub>: lower bound of e.
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 $e_{min}$  and  $e_{max}$  are prescribed by the geometry of the granulate, if we exclude grain crushing.

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 $e_{min}$  and  $e_{max}$  are prescribed by the geometry of the granulate, if we exclude grain crushing.

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These requirements can be fulfilled e.g. by the function

$$h = -\frac{c_4 + c_5\sigma}{e - e_{min}} . \tag{19}$$

Image: A math a math

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$$\frac{e_c - e}{\epsilon} \tag{20}$$

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It implies that compressibility depends also on dilatancy  $\epsilon$ .

We distinguish between dense  $(e < e_c)$  and loose  $(e > e_c)$  sand.

Dense sand has a tendency to loosening and loose sand has a tendency to get denser  $\rightsquigarrow$  a loose sand is more compressible than a dense one. In accordance, equation (18) implies:

- compressibility of dense sand increases with increasing  $\epsilon$
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Distinguish between the following compression lines  $e(\sigma)$ :

red: hydrostatic compession

blue: compression with a large deviatoric component,

$$\mathbf{D} = \begin{pmatrix} -2 & 0 & 0\\ 0 & 0.7 & 0\\ 0 & 0 & 0.7 \end{pmatrix}$$
(21)

green: critical state line,  $e_c(\sigma)$ starting at a dense state:  $e = 0.75 < e_{c0}(= 0.90)$ loose state:  $e = 0.95 > e_{c0}(= 0.90)$  Distinguish between the following compression lines  $e(\sigma)$ :

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#### Consolidations with various deviatoric parts



Compression curves calculated with barodesy, calibrated as shown

Prof. Dimitrios Kolymbas, Universität Innsbruck Barodesy - A new perspective of hypoplasticity

Interesting implication of equation (18) is obtained when the denominator vanishes:

This is obtained for a particular void ratio  $e = \hat{e}$ , that depends on  $\epsilon$ .

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#### Special case of equation (18) for $e \rightarrow e_c$ and $\epsilon \rightarrow 0$ :

The fraction then reads 0/0.

The compression curve is then the Critical State Line (CSL).

To determine the value of the fraction in the limit, we check, which limit transition prevails.

The transition  $e \rightarrow e_c$  can occur before the transition  $\epsilon \rightarrow 0$ , and thus prevails.

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$$\lim_{e \to e_c, \epsilon \to 0} \frac{e_c - e}{\epsilon} = 0$$
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$$\frac{d\sigma}{de_c} = -\frac{c_4 + c_5\sigma}{(1 + e_c)(e_c - e_{min})}$$
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Integration  $\rightsquigarrow$  equation of the CSL :

$$e_c(\sigma) = \frac{e_{min} + B}{1 - B} \tag{24}$$

with the abbreviation

$$B := \frac{e_{c0} - e_{min}}{e_{c0} + 1} \left(\frac{c_4 + c_5\sigma}{c_4}\right)^{-\frac{1 + e_{min}}{c_5}} .$$
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#### Critical State Line



Figure 3.32: Isotropic compression curves starting from different relative densities and critical states for Toyoura Sand; data digitalized from Ishihara and Verdugo

$$f = \epsilon + c_3 e_c$$
(26)  
$$g = -c_3 e$$
(27)

Hence, barodetic constitutive equation for sand reads:

$$\overset{\circ}{\mathbf{T}} = -\frac{c_4 + c_5 \sigma}{e - e_{min}} \left[ (\epsilon + c_3 e_c) \mathbf{R}^0 - c_3 e \mathbf{T}^0 \right] \dot{\varepsilon} , \qquad (28)$$

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$$\begin{split} nrmD &= norm(D, 'fro'); \ D0 &= D/nrmD; \ trD0 &= trace(D0); \\ nrmT &= norm(T, 'fro'); \ T0 &= T/nrmT; \\ c1 &= c1^*exp(c5^*trD0); \\ R &= -expm(c1^*D0); \ nrmR &= norm(R, 'fro'); \ R0 &= R/nrmR; \\ h &= -(c3+c4^*nrmT)/ \ (e-emin); \\ B &= (ec0-emin)/(ec0+1)^*((c3+c4^*nrmT)/c3)(-(1+emin)/c4); \\ ec &= (emin + B)/(1-B); \\ f &= trD0 + c2^*ec ; \ g &= -c2^*e ; \end{split}$$
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At that, experimental results are burdened by errors.

Therefore, calibration means optimization.

Also for barodesy, an optimized calibration procedure is still missing.

Here: only rough estimation of the material constants for Hostun sand:

 $c_1 \approx -1.05, c_2 \approx -2.3, c_3 \approx 28, c_4 \approx 465$  kPa,  $c_5 \approx 1$ .

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# Limit cycles and shake-down

With this equation and the condition  $|\mathbf{T}^0| = 1$  we can determine for a given  $\mathbf{D}^0$  the stress direction  $\mathbf{T}^0$  of the corresponding cyclic state and also the pertaining cyclic void ratio  $\check{\mathbf{e}}(\sigma)$ .



# Limit cycles and shake-down

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Figure - Evolution of void ratio with small stress cycles Rive Prof. Dimitrios Kolymbas, Universität Innsbruck Barodesy - A new perspective of hypoplasticity

# Stress paths for $P \varepsilon P$



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## **Response envelopes**



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# Simulation of oedometer test



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# Simulation of drained triaxial test



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# Simulation of undrained triaxial test



# Simulation of cyclic undrained triaxial test



## Simulation of undrained simple shear test


## Simulation of drained simple shear test



## Simulation of drained simple shear test



Thank you!

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