



### Numerical analysis of a reinforced backfill under dynamic loading

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### Outline

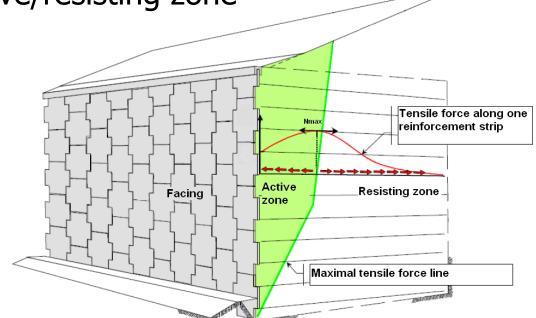
- Introduction of the topic
- Presentation of a full-scale experimentation (2008)
- Numerical model using 3D-FEM
- Focus on apparent friction coefficients
- Perspectives

#### Introduction

#### Mechanically Stabilized Earth walls :

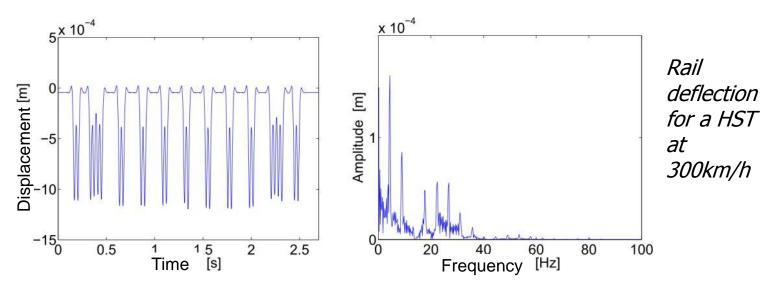
 Stability ensured by friction between steel reinforcement and backfill





#### Introduction

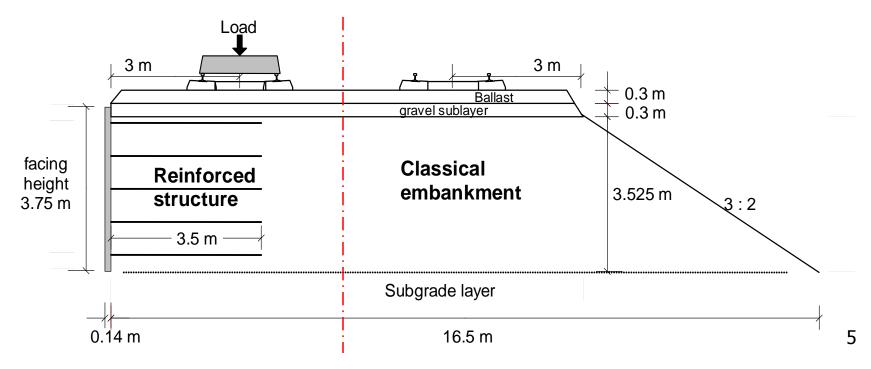
- High speed train: dynamic loading
- Time scales:
  - Time of passing of a single HST
- Space scales:
  - Local : interface behavior
  - **Global** : modes of vibration of the whole embankment



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Presentation of a full-scale experimentation (2008)

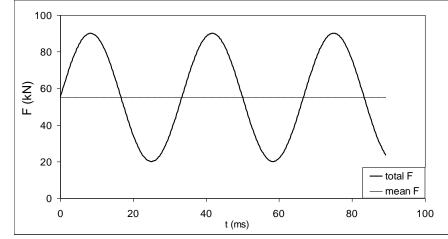
- Instrumented one-scale embankment (CER, IFSTTAR, SNCF)
- Some experimental results already published

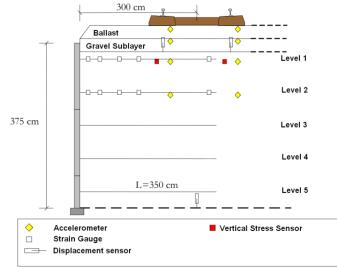


## Presentation of a full-scale experimentation (2008)

#### Dynamic loads

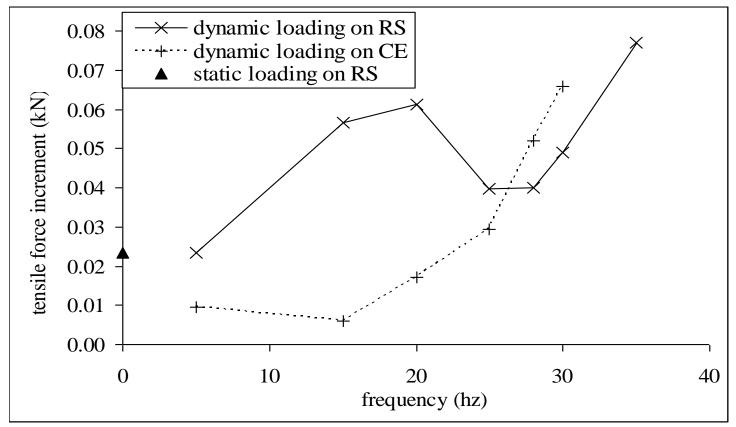
- A static part
- A dynamically varying overloading
- In harmonic steady state
- Several sensors:
  - Accelerometers
  - Stresses sensors
  - Strain gauges glued on the reinforcements => tensile force
  - Displacements H and V





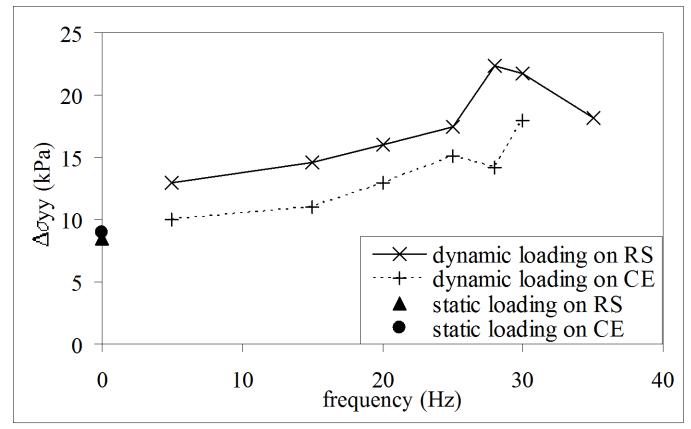
#### Variation with frequency

 Mean incremental Tensile Force in the first 1.5m of a 1<sup>st</sup> layer strip.



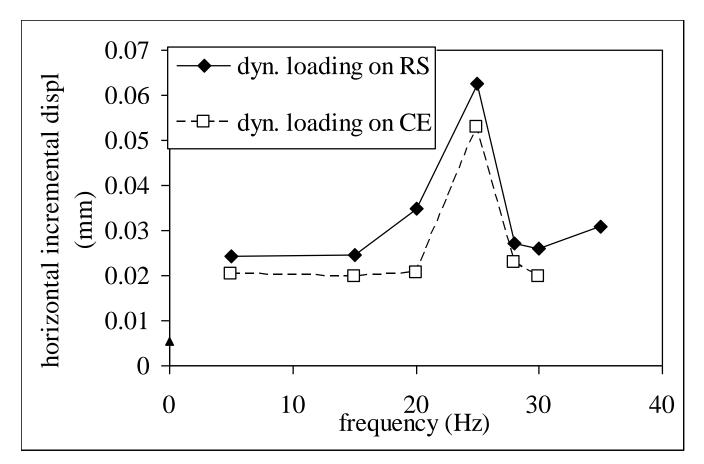
#### Variation with frequency

 Spectrum of vertical stress increment at sublayer/backfill interface and right below the sleeper



#### Variation with frequency

Mean horizontal facing displacement of the top 2.6 m



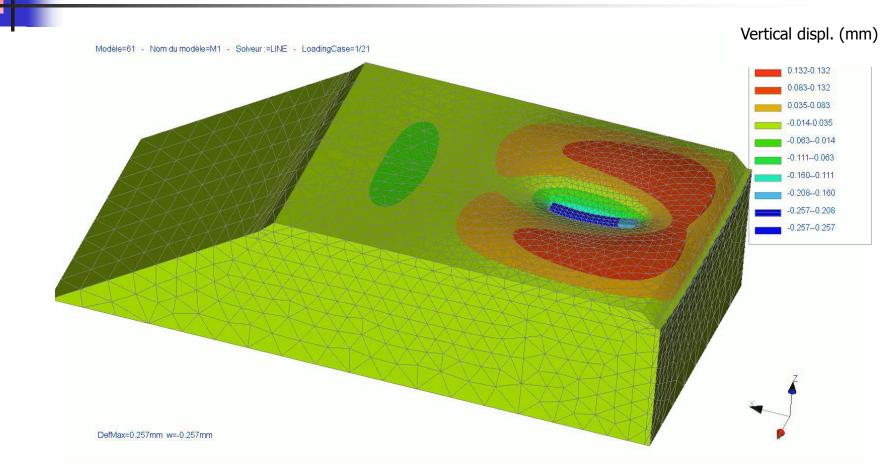
#### **Experimental conclusions**

- Dynamic loading is sensible for the first two layers of reinforcements
- At this depth:
  - Tensile forces and displacements are strongly frequency-dependent but have small amplitude
  - Increments of vertical stress are less frequencydependent but have an important amplitude

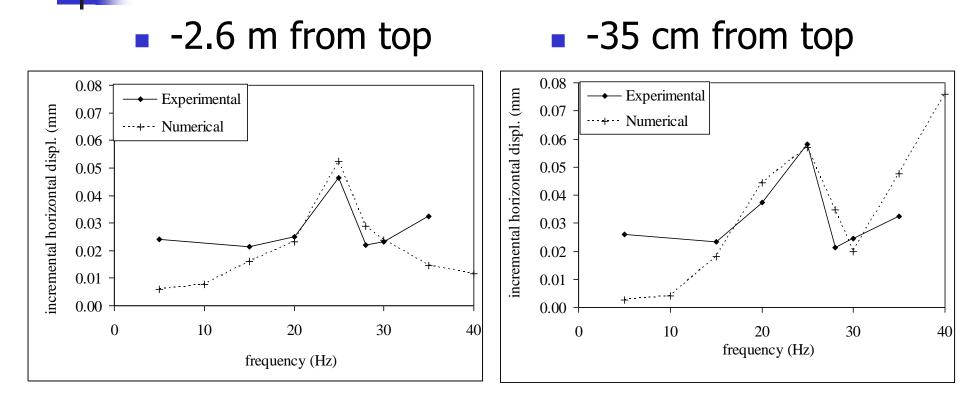
#### **3D-FEM model**

- CESAR-LCPC software
- Only dynamic over-loading modeled using visco-elastic constitutive law.
- Facing model: transversal isotropic
- Young's modulus varying with depth (to take into account actual earth pressure)
- Discrete reinforcements with interface stiffness consideration

#### **Numerical Model**

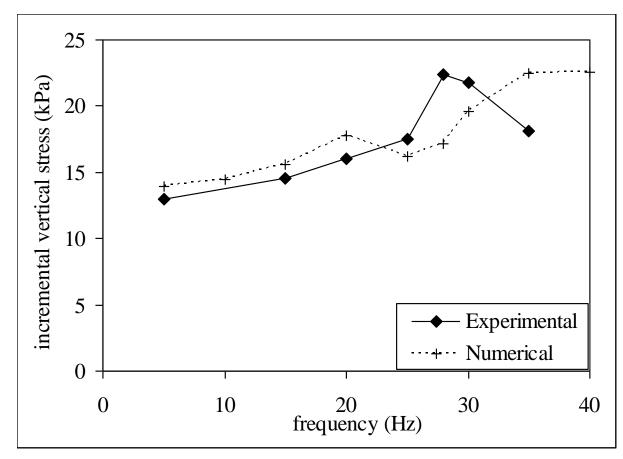


## Results: facing horizontal displacements



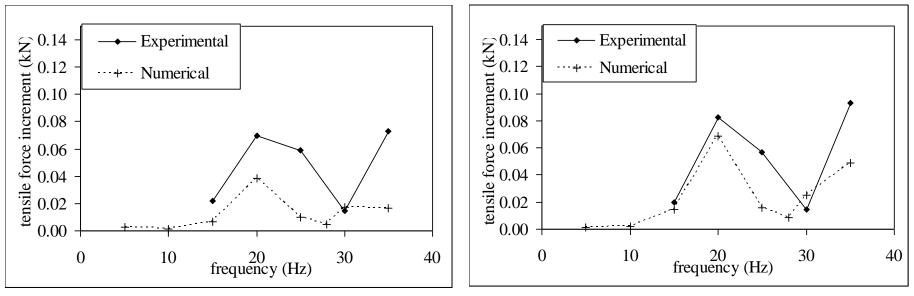
#### Results : vertical stresses

Incremental vertical stress at the backfill/sublayer interface



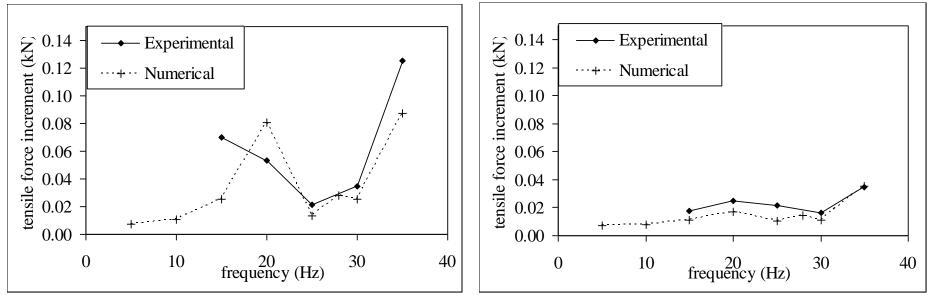
#### **Results: tensile forces**

- Top layer reinforcement, at 10 cm from facing
- Top layer reinforcement, at 30 cm from facing



#### **Results: tensile forces**

- Top layer reinforcement, at 1.4 m from facing
- Top layer reinforcement, at 3.35 m from facing



# Conclusion on the numerical model

- Numerical model validated
- Will be used to investigate dynamic behavior more accurately.

#### Apparent coefficient of friction

- Focus on local reinforcement-ground interface behavior
- Tensile force in a point x of the reinforcement:  $dN = 2.b.\tau(x,t).dx$
- From a static point of view, one often defines a friction coefficient  $\mu$ , so that:  $\tau(x) = \mu . \sigma_v(x)$

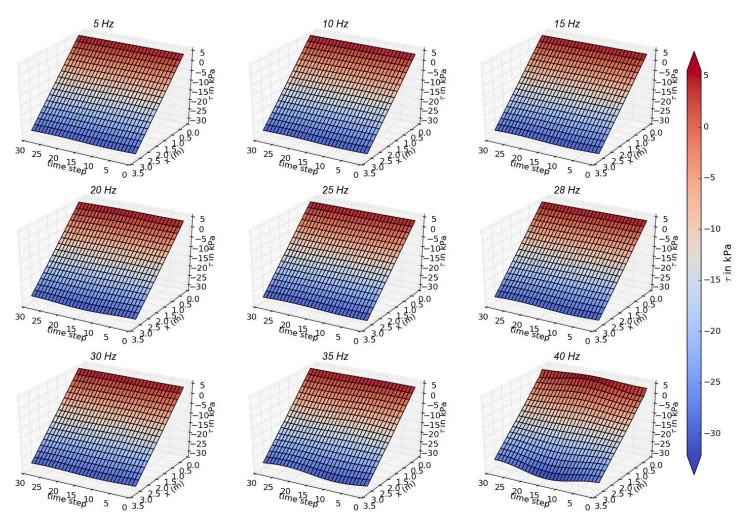
### Apparent coefficient of friction

- µ is often used in design to estimate the maximal value of the mean friction coefficient along a reinforcement strip, at failure (pull-out tests)
- µ takes into account the effect on restrained dilatancy on low confining pressure
- $\mu < \mu^*$  with  $\mu^*$  given by the norm

#### In dynamic loading??

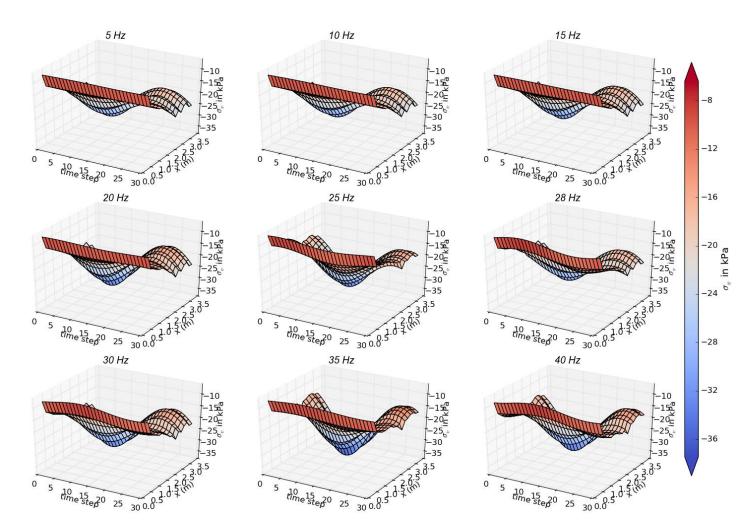
µdynamic\_loading defined by total shear stress and total vertical stress acting along the strip

#### Total shear stress along a first layer reinforcement (1/2b dN/dx)



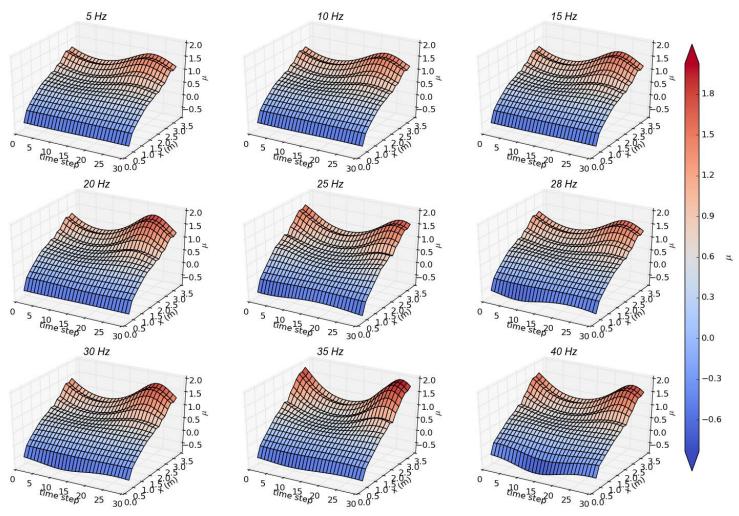
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## Total vertical stress along a first layer reinforcement



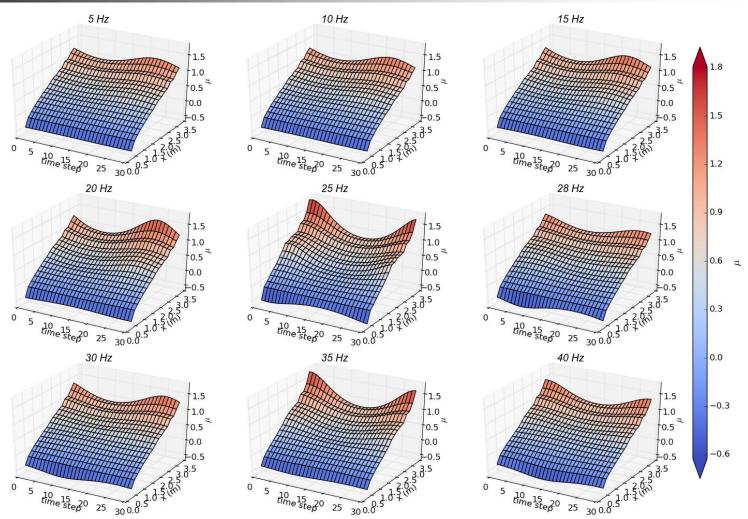
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#### Apparent coefficient of friction along a 1st layer reinforcement



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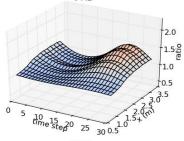
#### Apparent coefficient of friction along a 2nd layer reinforcement



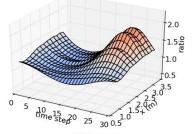
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## Comparison with a static load with same amplitude

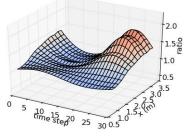
Plot the ratio µdynamic\_loading/µstatic

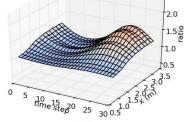




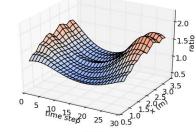




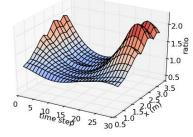


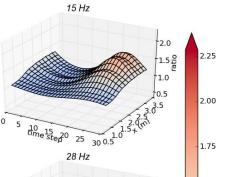


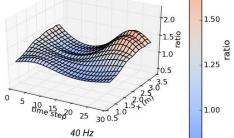


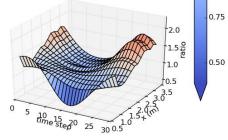


35 Hz









### Apparent friction coefficient

#### Conclusions

- Behavior of the interface different than in static case
- μdynamic variations depends on σ<sub>v</sub>, incremental
- µdynamic can reach values up to 2.2 times greater than in static case (for 35 Hz), but not in each point of the strip nor at each time of a period.
- Dynamic behavior not critical for a design point of view, for a time scale corresponding to a single HST passing.

#### Perspectives

Computations:

- Actual HST loading
- Real structure
- Long term studies (interface fatigue)
- Numerical developments:
  - Development of a interface-fatigue constitutive model

### Thank you for your attention!

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