

on (a,b,c)

a. 'thermodynamic state'

b. 'critical state',

c. 'rate and state'

by: Itai Einaiv, University of Sydney

thanks

François Guillard, University of Sydney

Mario Liu, University of Tuebingen

Miles Rubin, Technion - Israel Institute of Technology

Alessandro Tengattini, University of Grenoble

Manolis Vevakis, University of New South Wales

thermodynamic state (pure solids)

Helmholtz free energy $f = f(\epsilon_{ij}^e)$

Rates of internal variables $\dot{\epsilon}_{ij}^e(\epsilon_{ij}^e, \dot{\epsilon}_{ij}) = \dot{\epsilon}_{ij} - \dot{\epsilon}_{ij}^p(\epsilon_{ij}^e, \dot{\epsilon}_{ij})$

1) Steady state $\dot{\epsilon}_{ij}^e(\epsilon_{ij}^e, \dot{\epsilon}_{ij}) \equiv 0$

Stress $\sigma_{ij}(\epsilon_{ij}^e) = \partial f / \partial \epsilon_{ij}^e \rightarrow \epsilon_{ij}^e \equiv \epsilon_{ij}^e(\sigma_{ij})$

3) From equations 1 and 2 $\dot{\epsilon}_{ij}^e(\sigma_{ij}, \dot{\epsilon}_{ij}) \equiv 0$

4) Rate independence $\dot{\epsilon}_{ij}^e(\sigma_{ij}, \lambda \dot{\epsilon}_{ij}) = \lambda \dot{\epsilon}_{ij}^e(\sigma_{ij}, \dot{\epsilon}_{ij}) \equiv 0$

or $\dot{\epsilon}_{ij}^e(\sigma_{ij}) \equiv 0$

failure state (pure solids)

Summary. Under the following three assumptions:

- (1) energy dependent only on elastic strain;
- (2) rate independence; and
- (3) steady state,

we find $\dot{\epsilon}_{ij}^e(\sigma_{ij}) \equiv 0$



'failure criterion'

$$F(\sigma_{ij}) \equiv 0$$

thermodynamic state (general soils)

Helmholtz free energy

$$f \equiv f(\varrho, \epsilon_{ij}^e, \dots)$$

Landau (1953)
de Gennes (1993)
Jiang-Liu (2009)



ϱ_{initial}

shaking
→
stress free

$$\epsilon_{ij}^e = 0$$



$\varrho_{\text{shaked}} > \varrho_{\text{initial}}$

thermodynamic state ('classical' soils)

Helmholtz free energy $f = f(\rho, \epsilon_{ij}^e)$

Rates of internal variables $\dot{\rho} = \rho \dot{\epsilon}_v$

$$\dot{\epsilon}_{ij}^e = \dot{\epsilon}_{ij} - \dot{\epsilon}_{ij}^p(\rho, \epsilon_{ij}^e, \dot{\epsilon}_{ij})$$

1) Steady state $\dot{\rho} = \rho \dot{\epsilon}_v \equiv 0$

$$\begin{aligned}\dot{\epsilon}_{ij}^e &= \dot{\epsilon}_{ij} - \dot{\epsilon}_{ij}^p(\rho, \epsilon_{ij}^e, \dot{\epsilon}_{ij}) \\ &= \dot{\epsilon}_{ij}^e(\rho, \epsilon_{ij}^e, \dot{\epsilon}_{ij}) \equiv 0\end{aligned}$$

2) Stress $\sigma_{ij} = \partial f / \partial \epsilon_{ij}^e + P_T \delta_{ij}$

$$P_T(\rho, \epsilon_{ij}^e) = - \frac{\partial(f/\rho)}{\partial(1/\rho)}$$


$$\epsilon_{ij}^e \equiv \epsilon_{ij}^e(\rho, \sigma_{ij})$$

Landau (1953)
de Gennes (1993)
Jiang-Liu (2009)

thermodynamic state ('classical' soils)

3) From equations 1 and 2 $\dot{\epsilon}_{ij}^e(\varrho, \sigma_{ij}, \dot{\epsilon}_{ij}) = 0$

since $\dot{\epsilon}_v = 0 \rightarrow \dot{\epsilon}_{ij}^e(\varrho, \sigma_{ij}, \dot{\epsilon}_s) = 0$

4) Rate independence $\dot{\epsilon}_{ij}^e(\varrho, \sigma_{ij}, \lambda \dot{\epsilon}_s) = \lambda \dot{\epsilon}_{ij}^e(\varrho, \sigma_{ij}, \dot{\epsilon}_s) \equiv 0$

critical state ('classical' soils)

Summary. Under the following three assumptions:

- (1) energy dependent on elastic strain and density;
- (2) rate independence; and
- (3) steady state,

we find



critical state 'line' $F(\varrho, \sigma_{ij}) \equiv 0$

$$e = \frac{\hat{\varrho} - \varrho}{\varrho}$$

critical state (the 'α' soil)

Summary. Under the following three assumptions:

- (1) energy dependent on elastic strain and density and a vector of internal variables α_{ij} ;
- (2) rate independence; and
- (3) steady state,



critical state 'field'

$$F(\varrho, \sigma_{ij}, \alpha_{ij}) \equiv 0$$

$$e = \frac{\hat{\varrho} - \varrho}{\varrho}$$

critical state ('crushable' soils)

Summary. Under the following three assumptions:

- (1) energy dependent on elastic strain and density and breakage B ;
- (2) rate independence; and
- (3) steady state,



critical state 'field' $F(\rho, \sigma_{ij}, B) \equiv 0$

critical state ('crushable' soils)

$$E_B(\varrho, \sigma_{ij}) = \frac{\partial f}{\partial B} \quad \tau(\varrho, B) = \frac{\varrho_{\max}(B) - \varrho}{\varrho_{\max}(B) - \varrho_{\min}(B)}$$

Tengattini et al
(2016)

$$F(\varrho, \sigma_{ij}, B) = \sqrt{\frac{E_B}{E_c}} - \gamma\tau \equiv 0$$

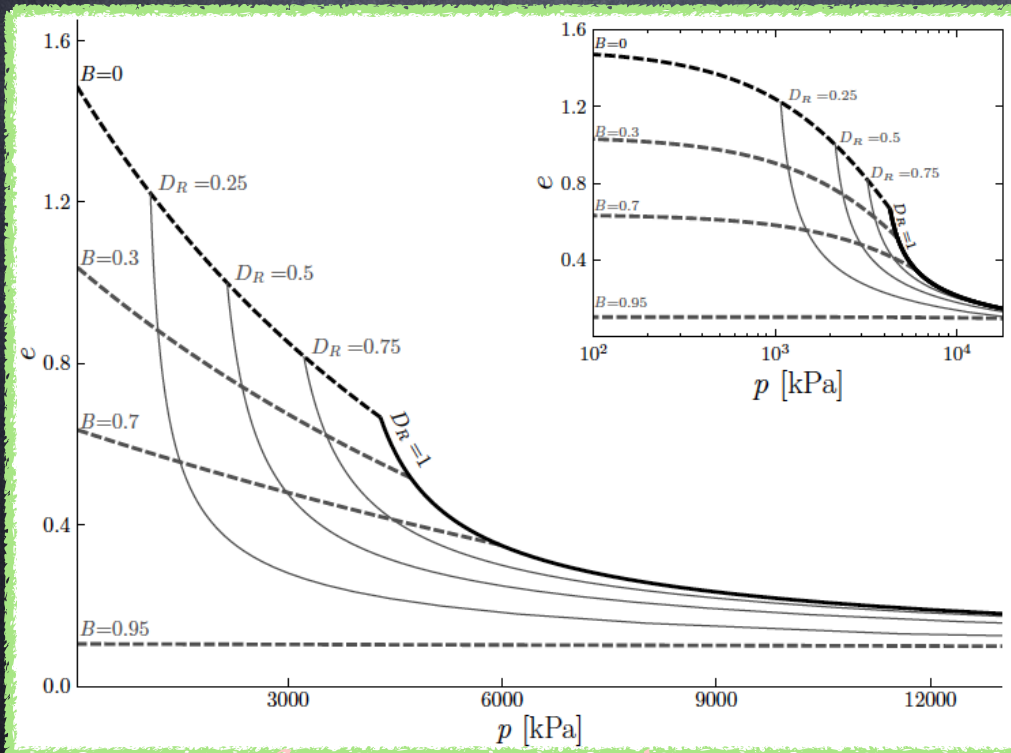


critical state ('crushable' soils)

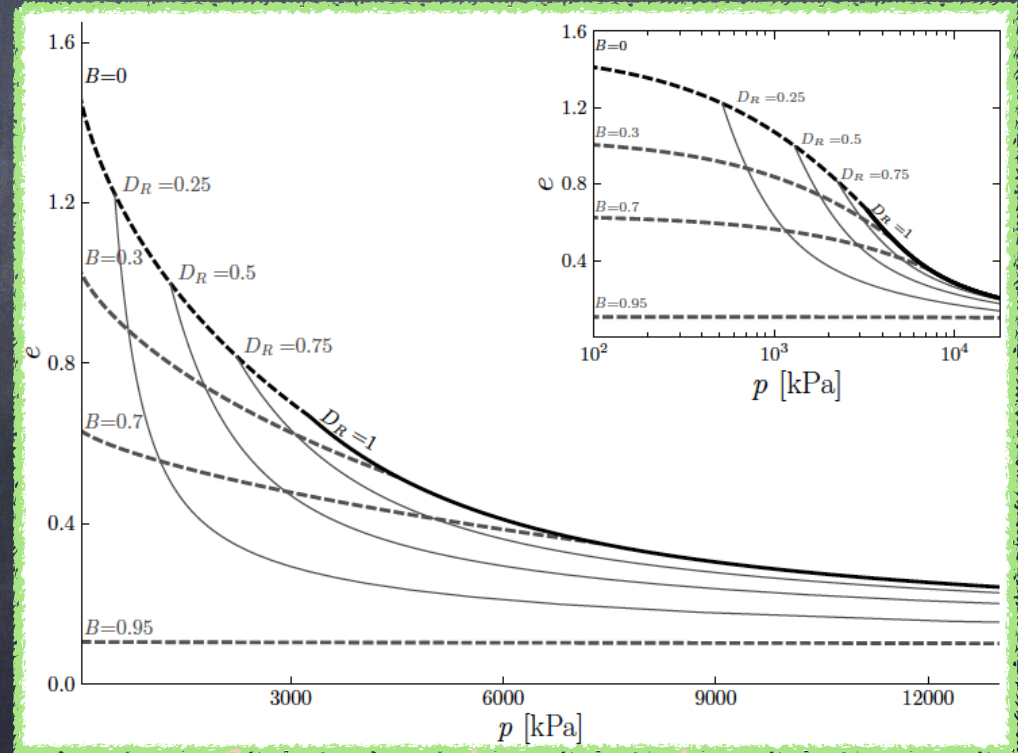
$$E_B(\varrho, \sigma_{ij}) = \frac{\partial f}{\partial B} \quad \tau(\varrho, B) = \frac{\varrho_{\max}(B) - \varrho}{\varrho_{\max}(B) - \varrho_{\min}(B)}$$

Tengattini et al
(2016)

$$F(\varrho, \sigma_{ij}, B) = \sqrt{\frac{E_B}{E_c}} - \gamma\tau \equiv 0$$

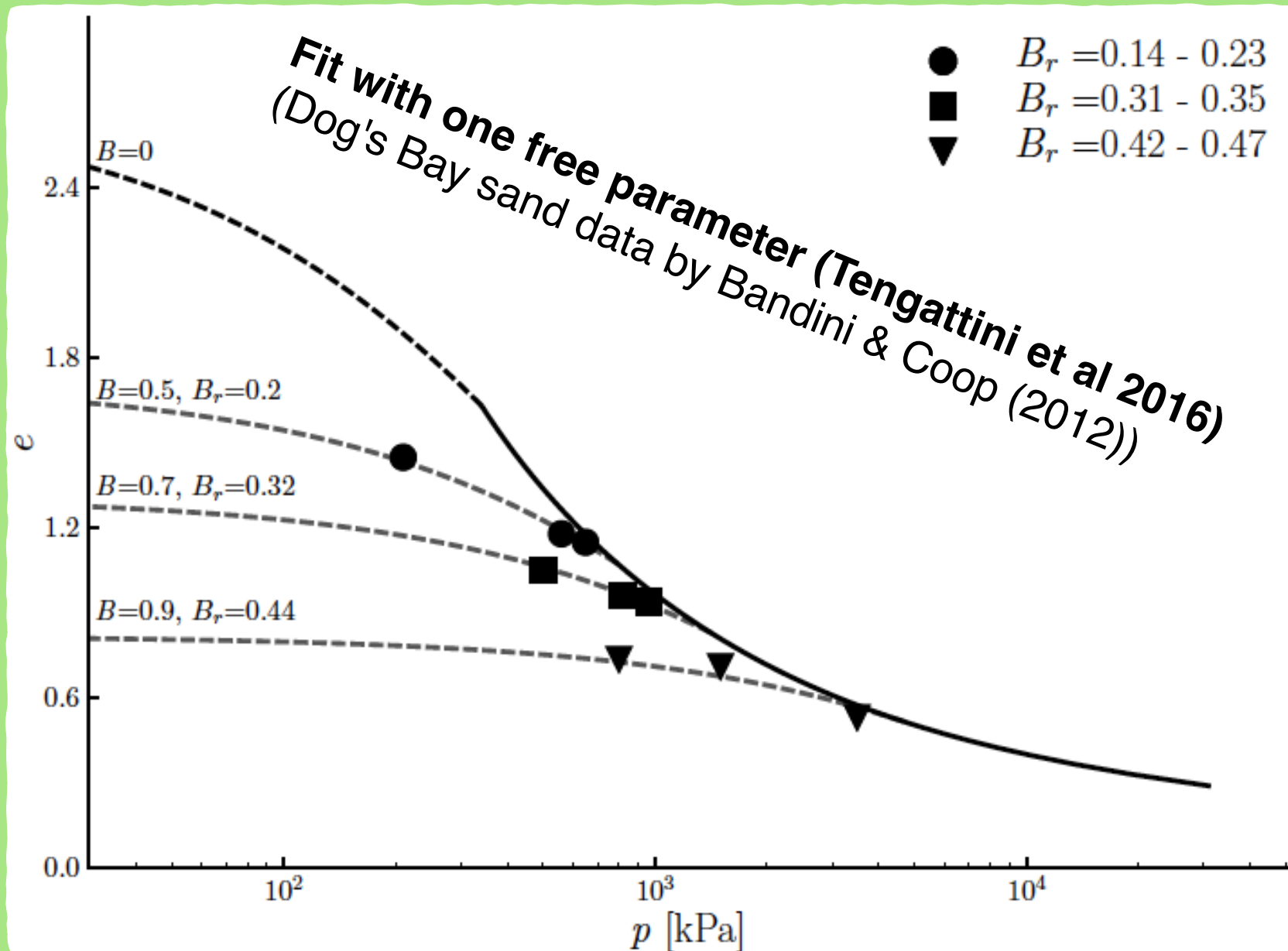


E_B from Linear Elasticity



E_B from Nonlinear Elasticity

critical state ('crushable' soils)

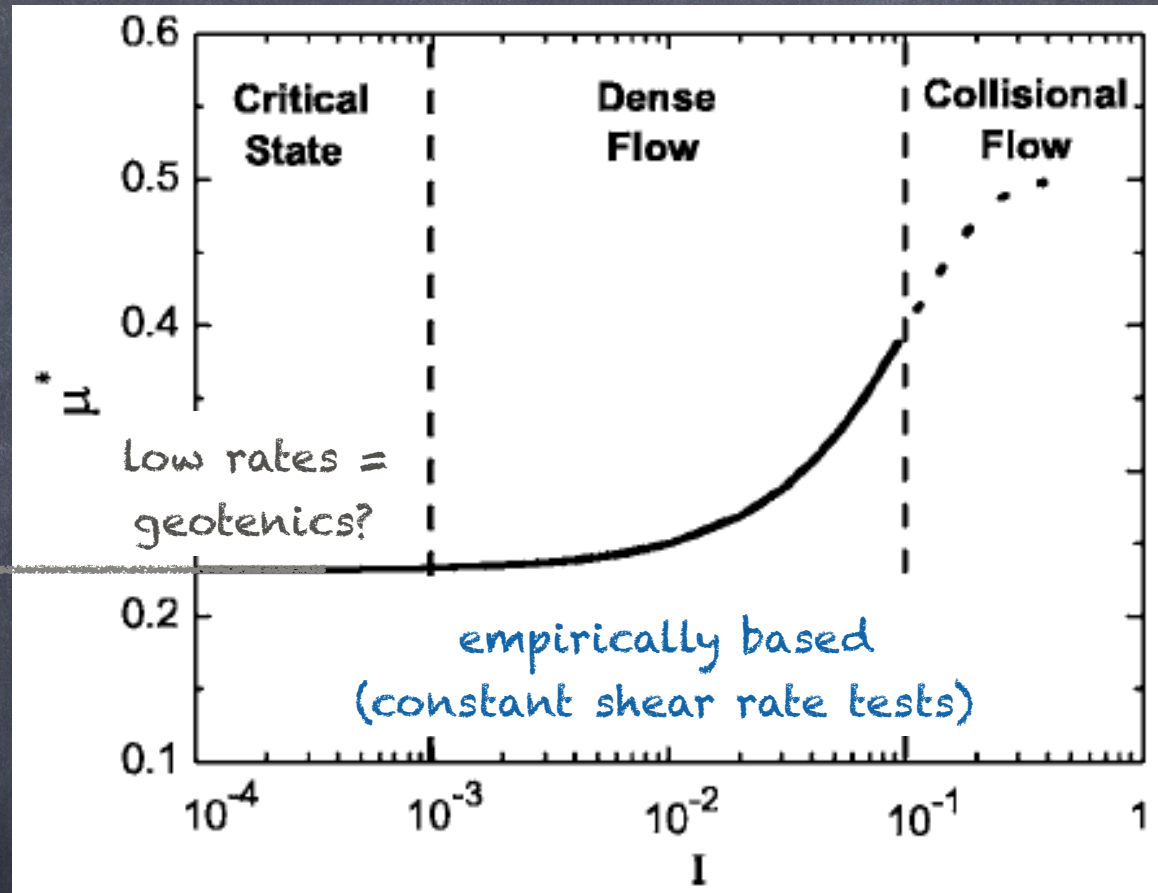


sub-conclusions

- 'Critical State Theory' (CST) builds on the assumption that steady state will eventuate at large strains under very low shear rates
- critical state is necessarily dependent on the form of thermodynamic energy

$\mu(I)$ -rheology

da Cruz et al
(2011)



$$I \equiv d\dot{\gamma} \sqrt{\frac{\rho}{\sigma_{ii}}}$$

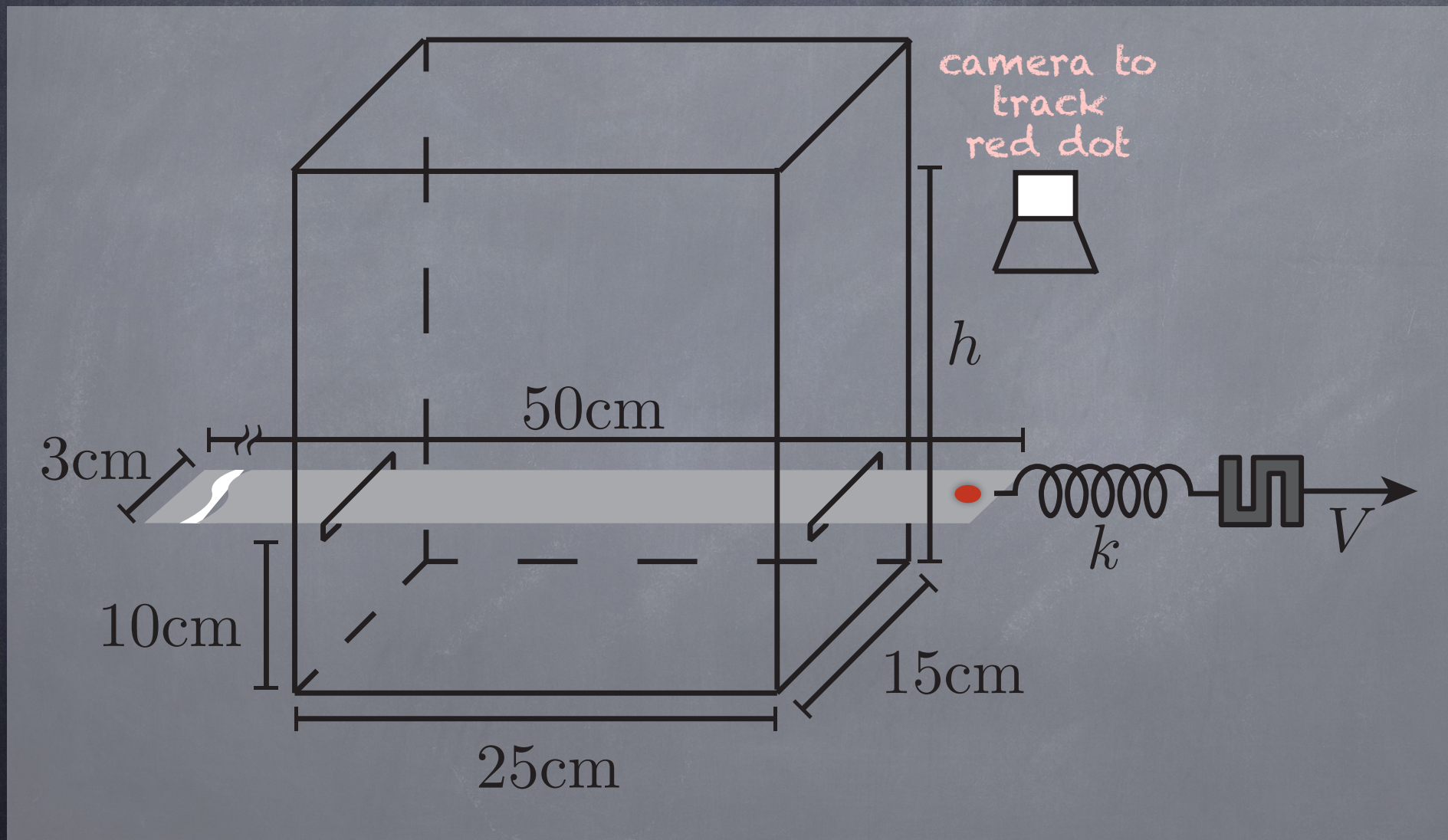
$$F(\rho, \sigma_{ij}) \equiv 0$$

$$F(\rho, \sigma_{ij}, \dot{\epsilon}_s) \equiv 0$$

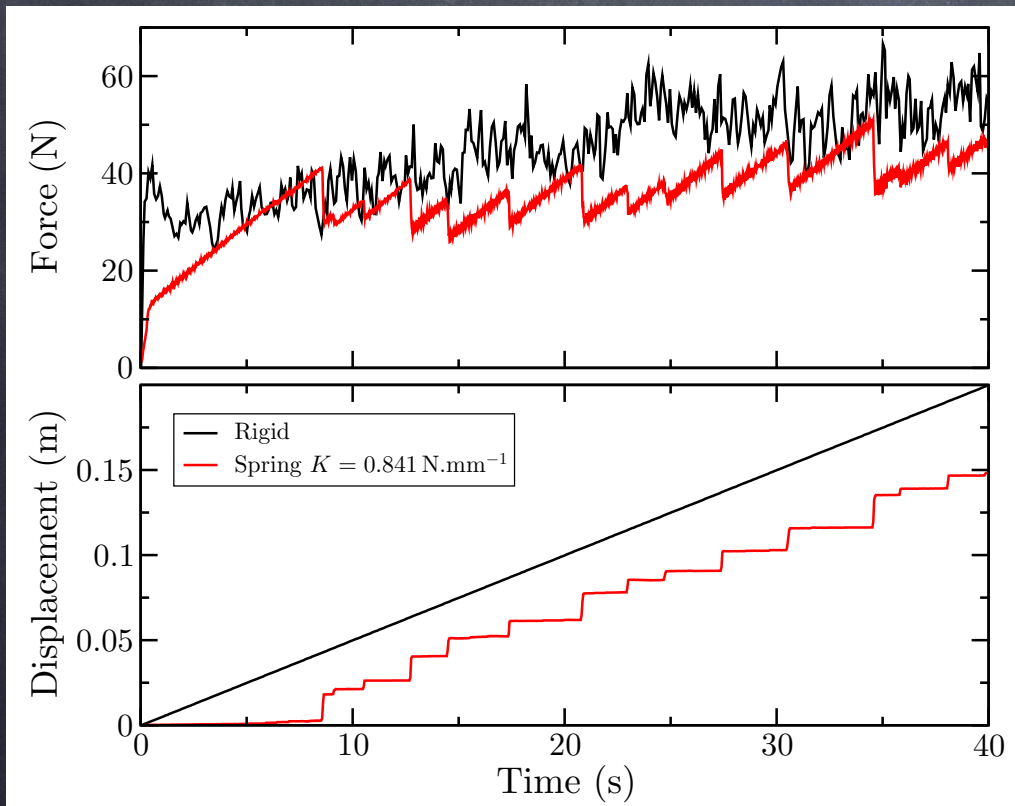
$$\tau_{xy} = \sigma_{yy} \mu(I)$$

$$\rho = \rho(I)$$

non-critical state (stick-slip)

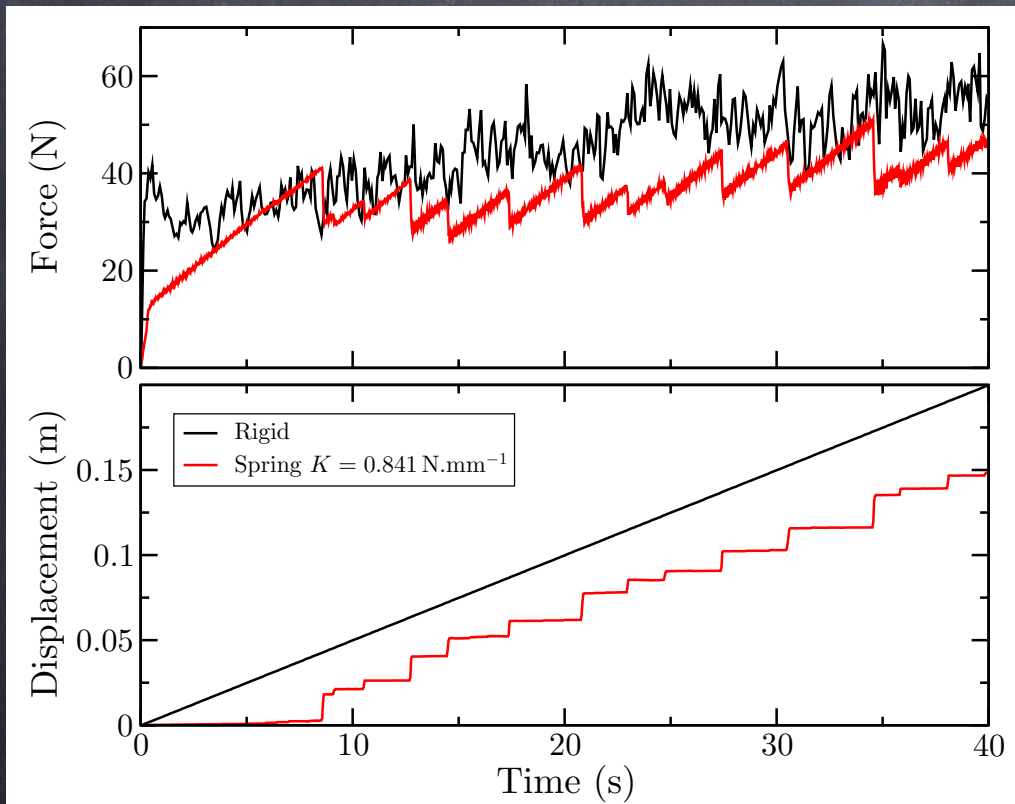


non-critical state (stick-slip)

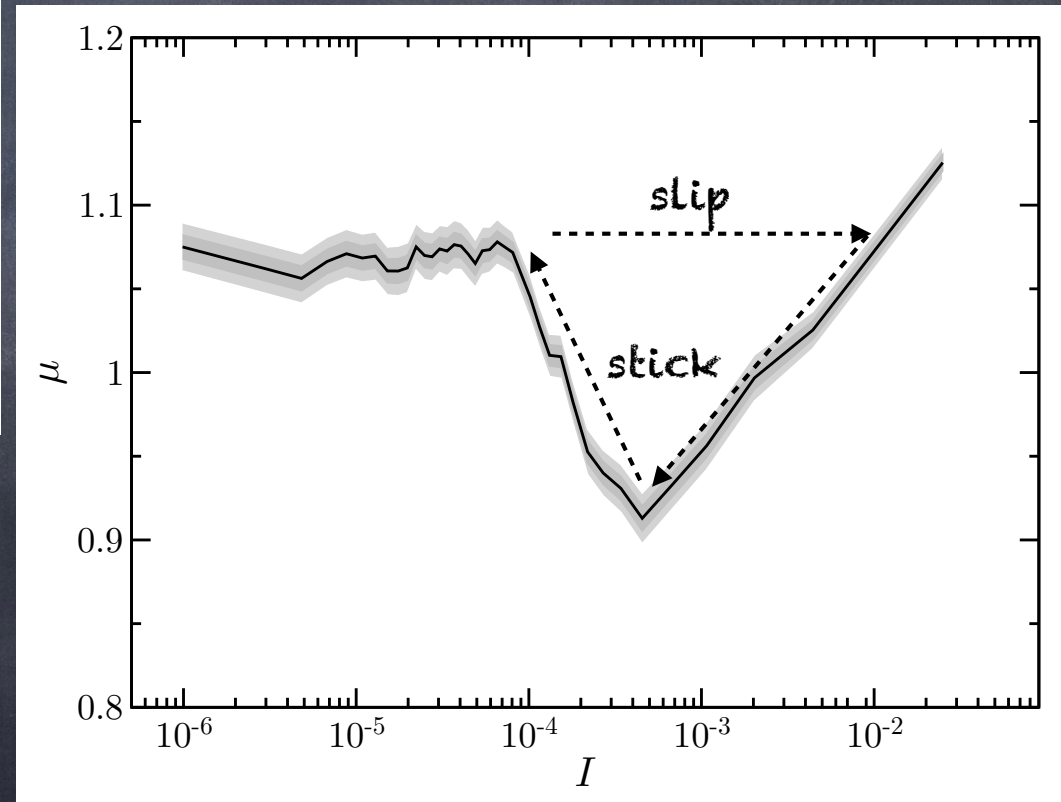


update $\mu(I)$?

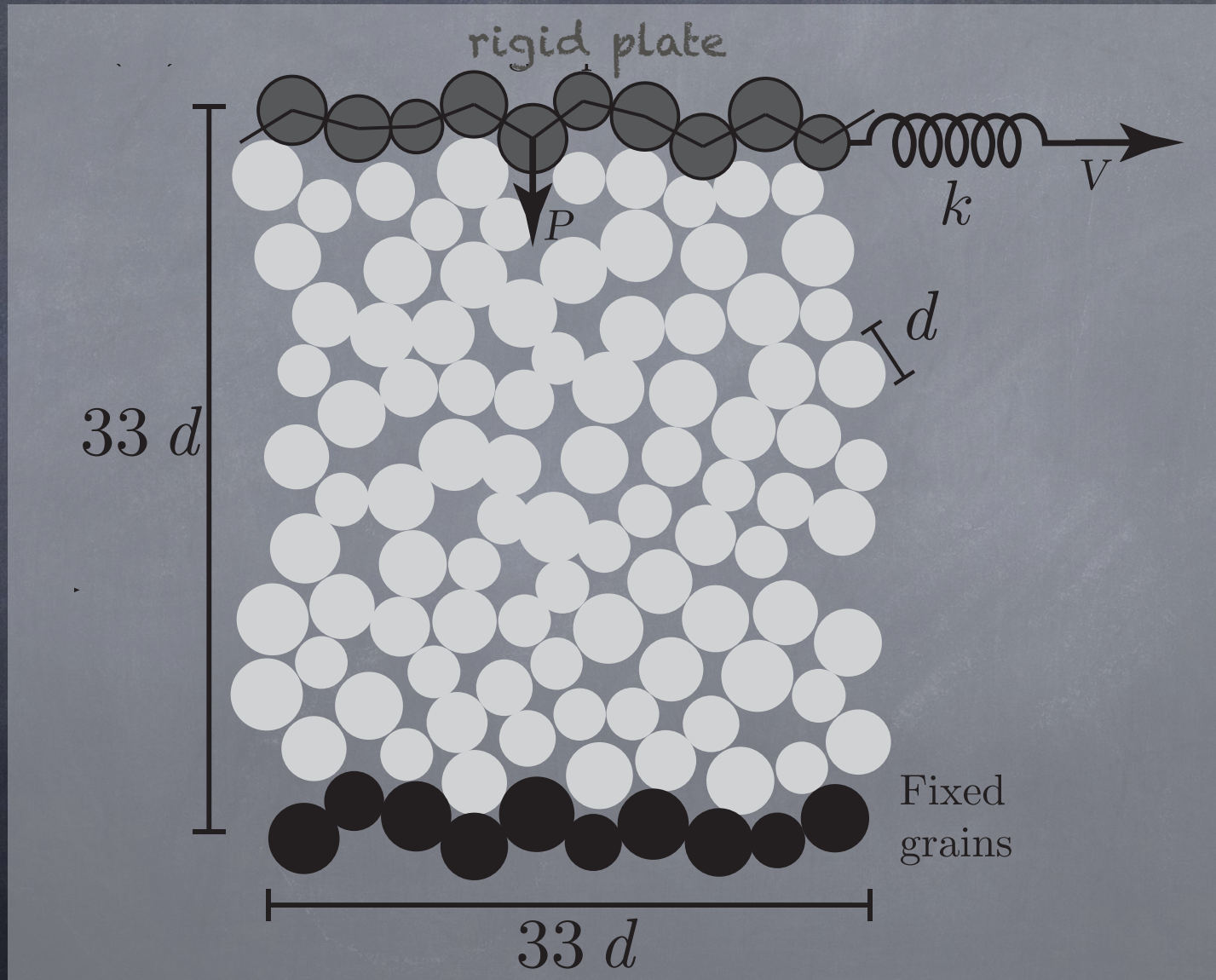
non-critical state (stick-slip)



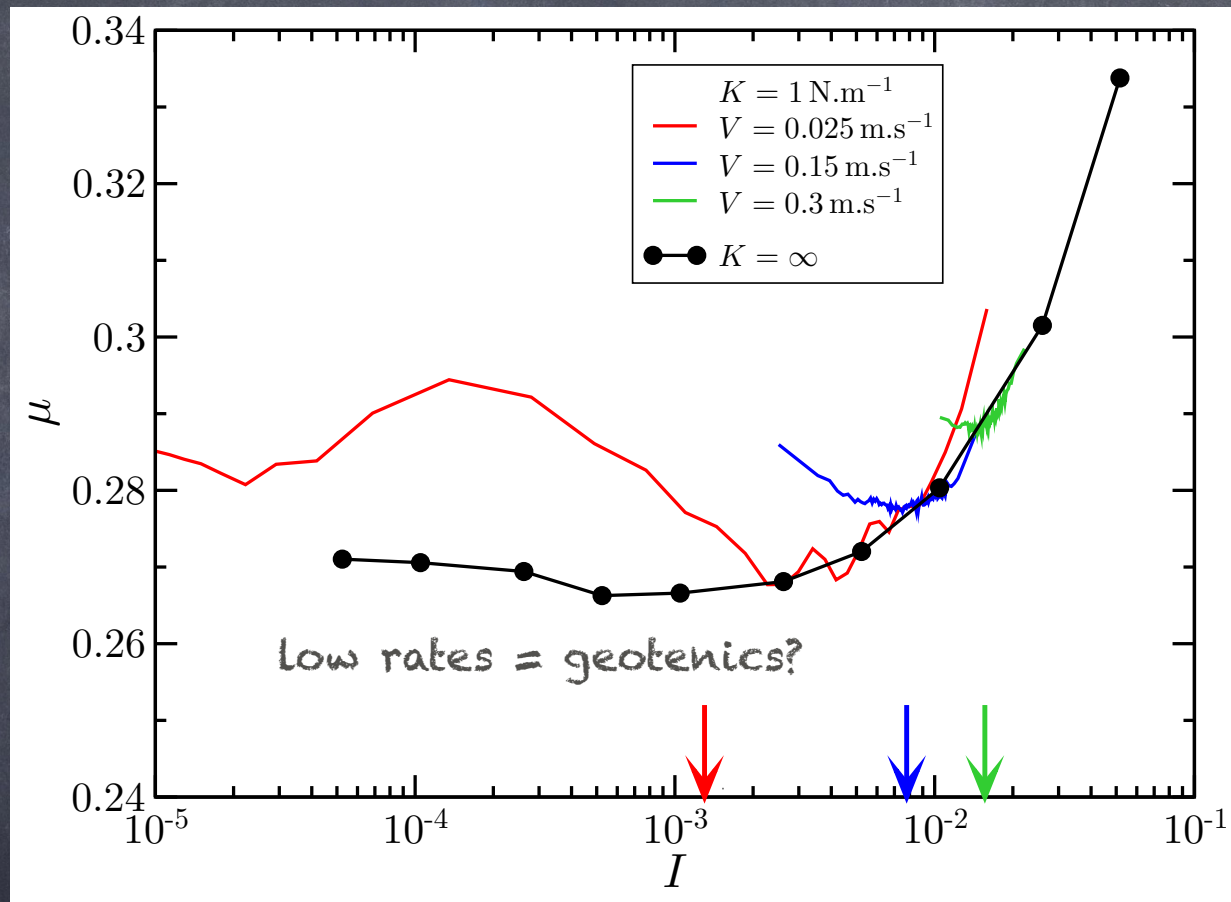
update $\mu(I)$?



non-critical state (stick-slip)



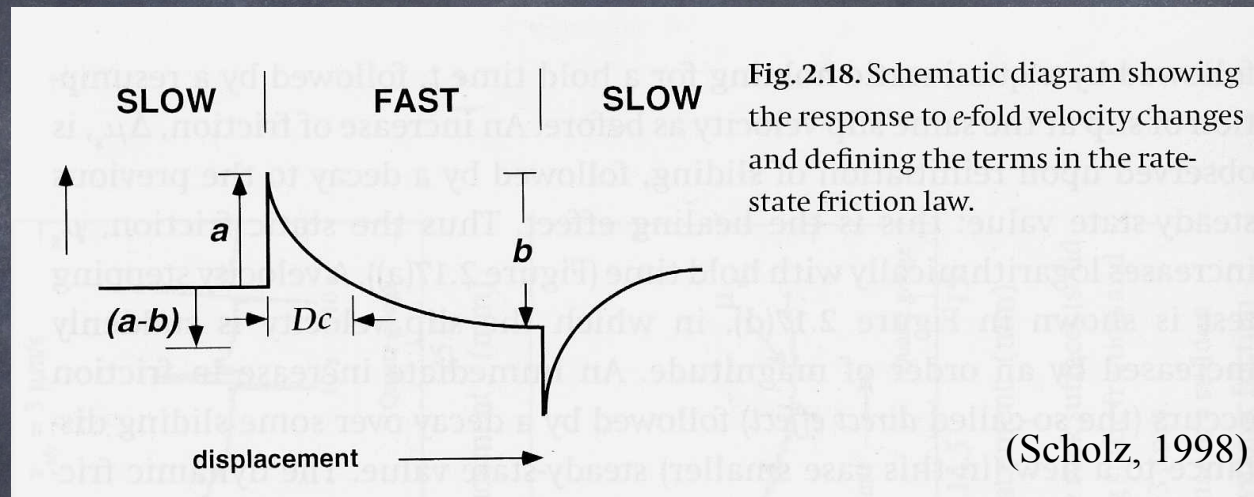
non-critical state (stick-slip)



- what will CST predict? $\rightarrow$ constant force
- update $\mu(I)$? $\rightarrow$ but no uniqueness

non-CST

(rate and state friction law)



$$\frac{\tau}{\sigma} \equiv \mu = \mu_0 + a \ln \left(\frac{V}{V_0} \right) + b \ln \left(\frac{V_0 \theta}{L} \right)$$

$$\dot{\theta} = 1 - \theta \frac{V}{L}$$

Dieterich (1981)
Ruina (1983)

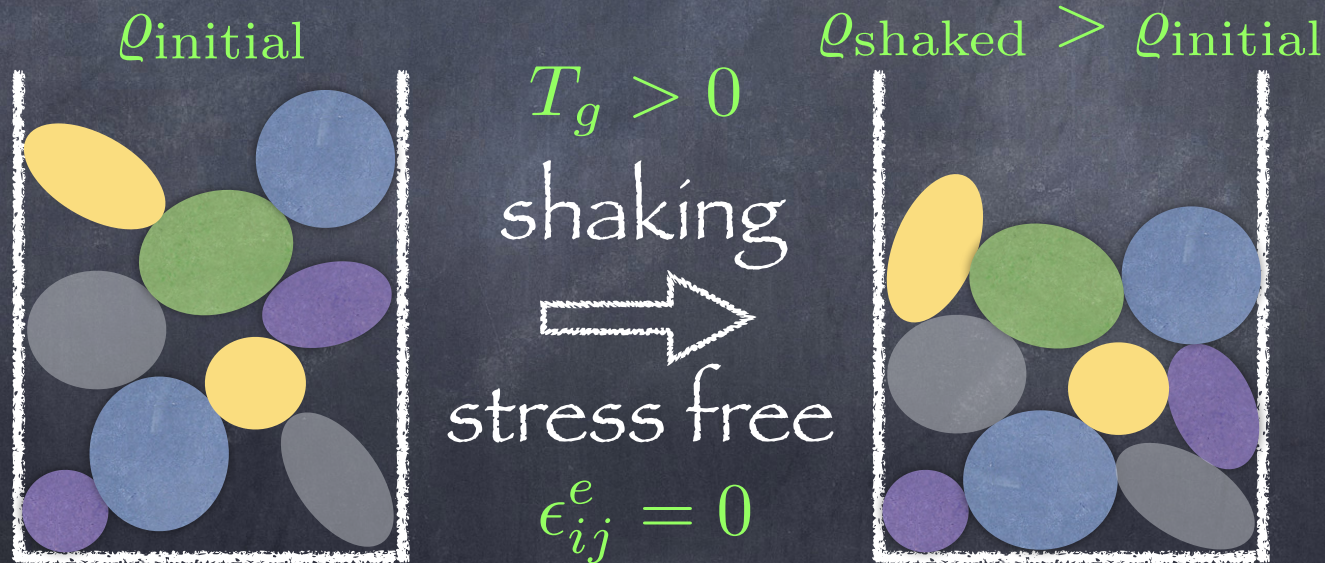
The critical slip distance L is interpreted as the sliding distance required to renew contact population. In this view θ represents average contact lifetime.

thermodynamic state (granular soils)

Helmholtz free energy

$$f \equiv f(\varrho, \epsilon_{ij}^e, T_g, \dots)$$

Landau (1953)
de Gennes (1993)
Jiang-Liu (2009)



Granular Solids Hydrodynamics

Helmholtz free energy $f = f(\varrho, \epsilon_{ij}^e, T_g)$

Stress $\sigma_{ij} = \partial f / \partial \epsilon_{ij}^e + P_T \delta_{ij} - \sigma_{ij}^D$

$$P_T(\varrho, \epsilon_{ij}^e, T_g) = - \frac{\partial(u/\varrho)}{\partial(1/\varrho)} \propto T_g^2$$

$$\sigma_{ij}^D \propto \dot{\epsilon}_s^2$$

$$\mu = \frac{\sigma_s}{\sigma_v} = \frac{\partial f / \partial \epsilon_s^e - c_1 \dot{\epsilon}_s^2}{\partial f / \partial \epsilon_v^e + c_2 T_g^2}$$

i.e., $\mu = \mu(\text{density, stress, 'rate and state'})$

Jiang-Liu (2009)

conclusions

- CST builds on the assumption that steady state will eventuate under very low shear rates
- which violates transient stick-slip observations
- adding granular temperature to describe thermodynamic state can resolve this issue