## "Effect of Brittle off-fault Damage on Earthquake Rupture Dynamics"

Harsha S. Bhat *ÉNS* Marion Thomas (Oxford)

Raul Madariaga ÉNS Alexandre Schubnel ÉNS Ares J. Rosakis CalTech Charlie Sammis USC

# Complexity?

- Small Scale Geometric Complexities ("Off-fault damage")
- \* Large Scale Geometric Complexities (branches, step-overs etc.)
- Structural (hydro-mechanical complexity)
- Loading (k<sup>-(1+H)</sup> stress distribution...)
- Friction (R-S law, Flash Heating, Thermal Pressurisation, Thermal Decomposition, Dilatant Strengthening ...)
  - \* Source (EQ, Slow EQ, LFE, VLFE, Tremors ...)
  - \* Speed (Migration, sub-shear, supershear ...)
  - \* Radiation (Spectral properties)

#### **Geometrical Complexities at Various Scales**









#### Zooming close to the fault plane : Hydro-Mechanical Complexities



#### **Modelling Earthquake Cycles : Missing ingredients**



Small Scale Geometric Complexities ("damage")
Large Scale Geometric Complexities (branches, stepovers etc.)





#### Role of off-fault damage (small scale geometric complexities) on a single earthquake rupture : Laboratory experiments



Bhat, Biegel, Rosakis and Sammis (2010) ; Biegel, Bhat, Sammis and Rosakis (2010)

### Homalite

Damaged Homalite

### **RUPTURE VELOCITY EVOLUTION Homalite/Damaged Homalite**



Bhat, Biegel, Rosakis and Sammis (2010) ; Biegel, Bhat, Sammis and Rosakis (2010)

#### Load and Loading rate dependency of brittle materials



**Micromechanical Damage Mechanics : General Idea** 

Coleman and Gurtin, 1967 ; Walsh 1965 ; Rice 1975 ; Budiansky and O'Connell, 1976

Let W be the Gibb's Free Energy density of a damaged solid whose damage "state" is characterized by D (scalar, vector or tensor). Then,

$$W = W^e(\bar{\sigma}) + N_v \Delta W^p(\bar{\sigma}, D)$$

Cracks, Voids, Dislocations etc.

Constitutive stress-strain relationship is given by,

$$\epsilon_{ij} = \frac{\partial W}{\partial \bar{\sigma}_{ij}} \qquad \qquad M_{ijkl} = \frac{\partial^2 W}{\partial \bar{\sigma}_{ij} \partial \bar{\sigma}_{kl}}$$

If the damaged solid solely consists of micro-cracks and  $\Gamma$  is the position along a microcrack describing its amount of local advance then the additional free energy due one crack is given by,

$$\Delta W^p = \frac{1 - \nu^2}{E} \int_{\Gamma} \left\{ K_I^2 + K_{II}^2 + \frac{K_{III}^2}{(1 - \nu)} - 2\gamma_s \right\} d\mathbf{I}$$

**Energy Release Per Unit Crack Area** 

State Evolution Laws :  $\frac{dD}{dt} = f(\sigma, \epsilon, \text{History}, ...)$ 

Represent the medium surrounding faults as an isotropic elastic solid that contains pre-existing monosized flaws, here represented by penny-shaped cracks that grow as wing cracks.

Hypothesis: under compression, tensile growing cracks induced frictional sliding are the major  $\sigma_1$  source of inelastic deformation in brittle material (shallow depths).



Nv penny shaped cracks per unit volume

- optimally oriented from a Coulomb friction perspective
- grow as soon as the shear stress on crack faces overcome the Coulomb frictional resistance.

Initial damage:

$$D_o = \frac{4}{3}\pi \left(\alpha a\right)^3 N_v$$

Damage when tensile wing-cracks have grown to length l:

$$D = \frac{4}{3}\pi \left( I + \alpha a \right)^3 N_v$$



Elastodynamics : Converting Static K<sub>1</sub> to a Dynamic K<sub>1</sub>

Bhat, Rosakis and Sammis (2012)

Freund (1973) showed that for an <u>unbounded body subjected to time independent</u> <u>loading</u>, the dynamic stress intensity factor at a running crack-tip can be expressed as a universal function of instantaneous crack-tip speed, v(t), multiplied by the equilibrium stress intensity factor for the given applied loading and the instantaneous amount of crack growth i.e.

$$K_I^{AS,d}\left(v,\bar{\sigma},\bar{\tau},D\right) \approx \frac{\left(1-v/c_R\right)}{\sqrt{1-v/c_p}} K_I^{AS}\left(\bar{\sigma},\bar{\tau},D\right)$$

In doing this we make the explicit <u>assumption that the characteristic time associated</u> with loading is much larger than the corresponding time associated with crack growth

## Incorporating proper micro-crack growth physics to capture dramatic strain-rate dependence of brittle materials



$$\frac{dD}{dt} = \left(\frac{3D^{2/3}D_0^{1/3}}{\alpha a}\right) \underbrace{v}_{\text{Crack Growth Law}}^{\text{Laboratory Based, rate}}$$

## Incorporating proper micro-crack growth physics to capture dramatic strain-rate dependence of brittle materials



Bhat, Rosakis and Sammis (2012)

#### **Dynamic Damage Mechanics**

Constitutive time integration procedure implemented using finite/spectral element methods



#### **Dynamic Damage Mechanics (Acoustic Emission)**

![](_page_16_Figure_1.jpeg)

Fully dynamic crack growth law allows for acceleration and deceleration of micro-cracks

![](_page_17_Figure_1.jpeg)

![](_page_18_Figure_0.jpeg)

<u>2D</u> right-lateral fault inside an homogeneous medium (Granite), where damage is only occurring on one side.

Evolution of the state parameter D that corresponds to the density of micro-cracks in the medium

D = 0 : Uncracked medium (linear elastic)D = 1 : All cracks are connected (granular)

The slip velocity along the fault plane

![](_page_19_Figure_1.jpeg)

Fault normal velocity Spectra

![](_page_20_Figure_2.jpeg)

Increasing fault normal distance

**Damaged side** 

![](_page_21_Figure_1.jpeg)

#### **Conclusions and Perspectives**

Physics based Micro-mechanical homogenisation of smaller scale geometric complexities (off-fault damage) allows/will allow us to capture :

- 1) Inter-play between on fault dissipation processes (friction) and off-fault dissipation processes (damage)
- 2) Dynamic evolution of the wave speeds in the medium (dynamic bi-material effect)
- 3) Generate high frequency radiation from a planar fault with uniform friction and stress
- 4) The coupling between larger scale geometric complexity and damage
- 5) The effect of permeability enhancement on post seismic response
- 6) Depth dependence of damage zone
- 7) Recovery of wave speeds due to crack healing