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## **ALERT Workshop 2017**

# Modelling of compaction grouting using the implicit MPM

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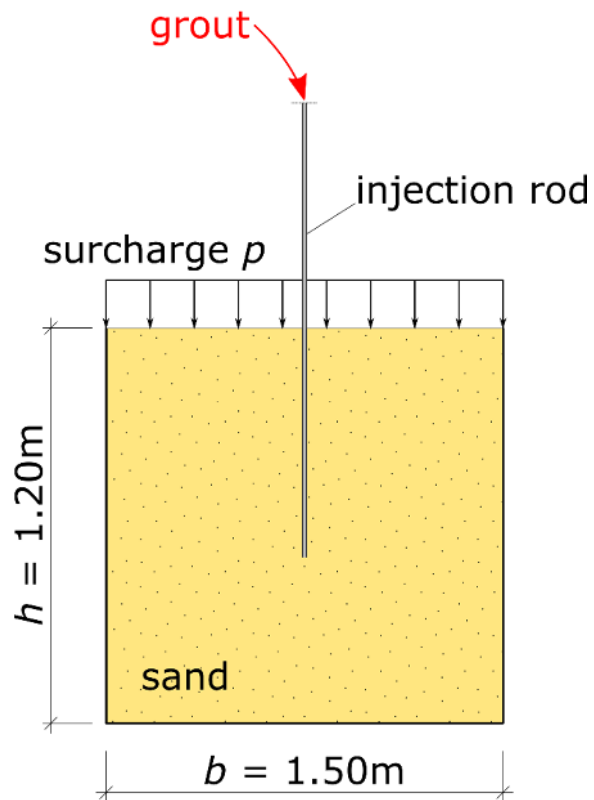
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# Compaction grouting

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## Definition (DIN EN 12715, October 2000)

“A displacement grouting method which aims at forcing a mortar of high internal friction into the soil to compact it without fracturing it.”

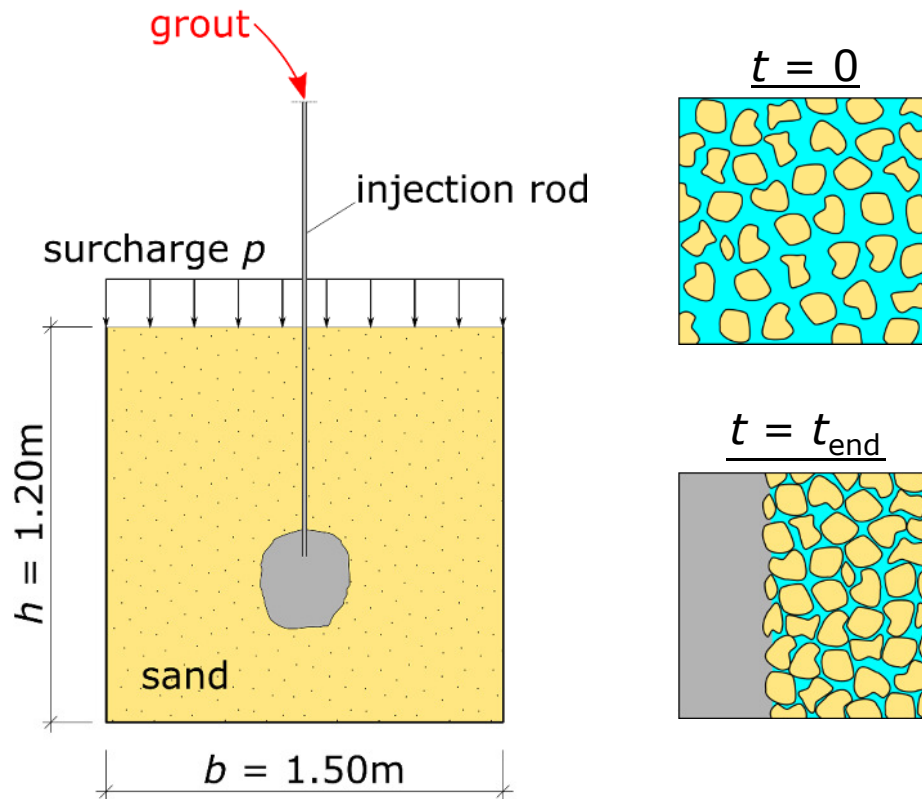


- Distinct grout-soil interface (filter cake)
- Displace the surrounding soil
  - increase the bulk density
  - increase the bearing capacity

# Compaction grouting

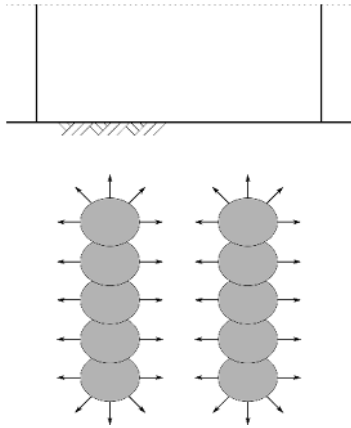
**Definition** (DIN EN 12715, October 2000)

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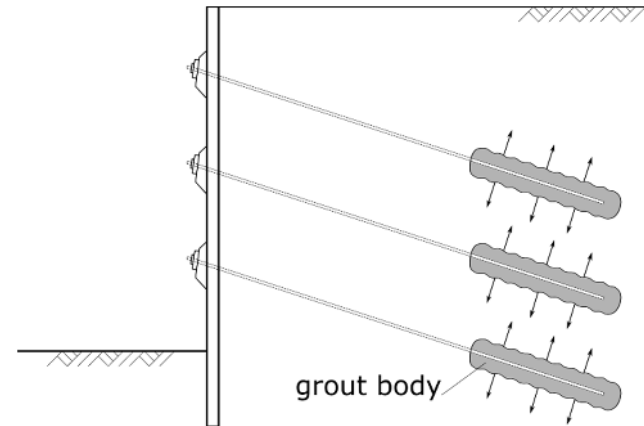


- Distinct grout-soil interface (filter cake)
- Displace the surrounding soil  
→ increase the bulk density  
→ **increase the bearing capacity**

# Compaction grouting – Fields of application

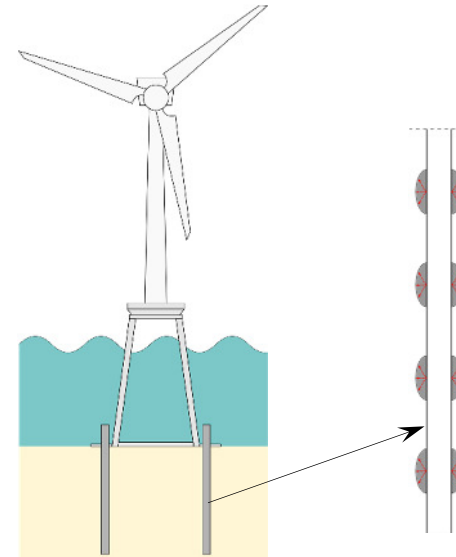
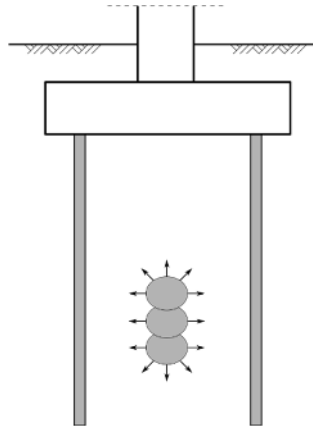


**Settlement control** (grouted columns)

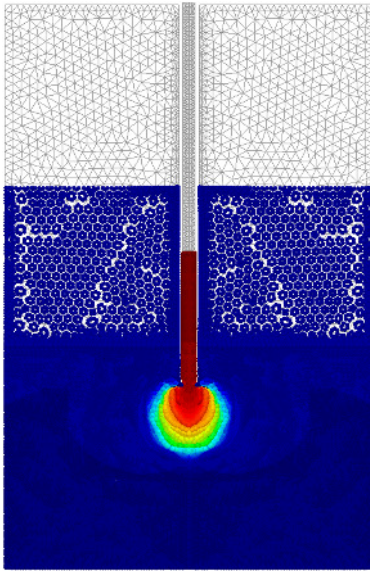


**Stabilisation** (ground anchors)

**Retrofitting**  
(bearing capacity of  
pile foundations)



# Challenges



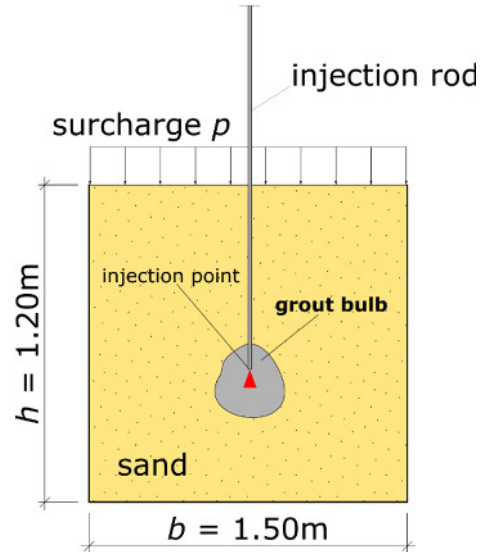
## Numerical simulation

Numerical method

- large deformations
- constitutive models

Software

- open source
- easily adaptable



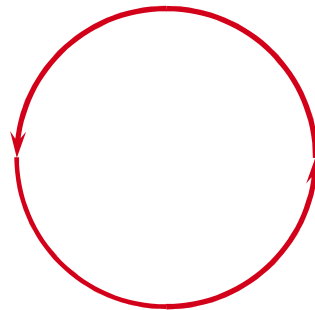
## Experiments

General concept

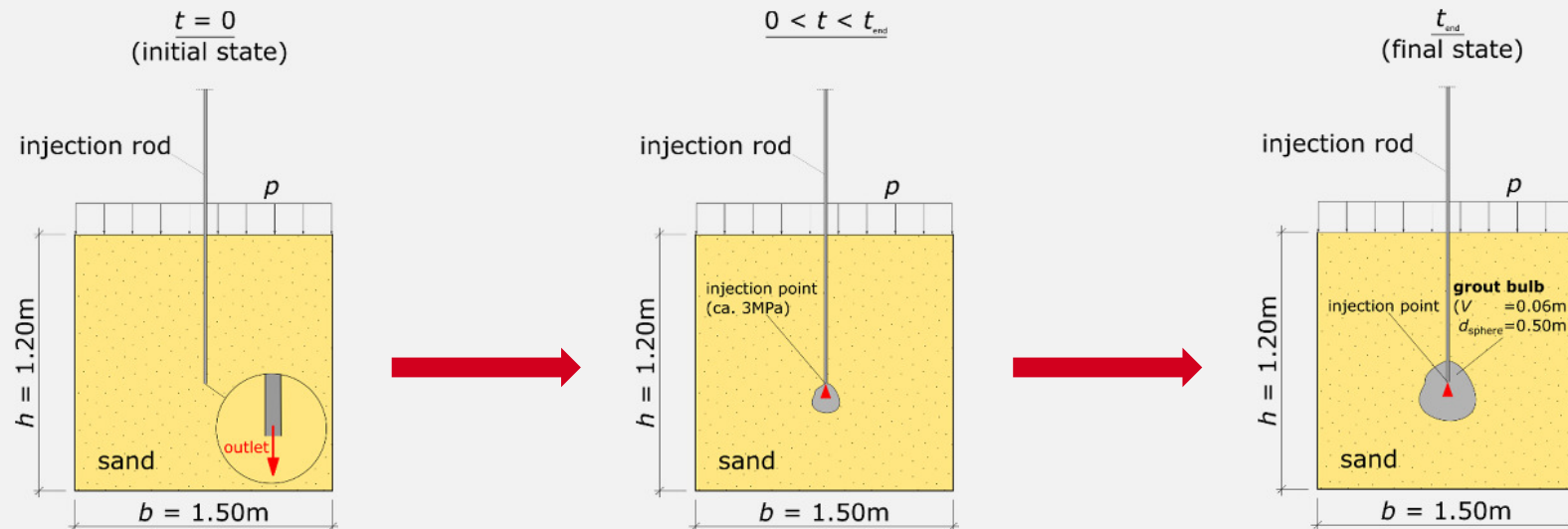
- setup
- procedure

Measurement methods

- Digital image processing (Aramis)



## Experimental setup (water saturated sand, drained condition)

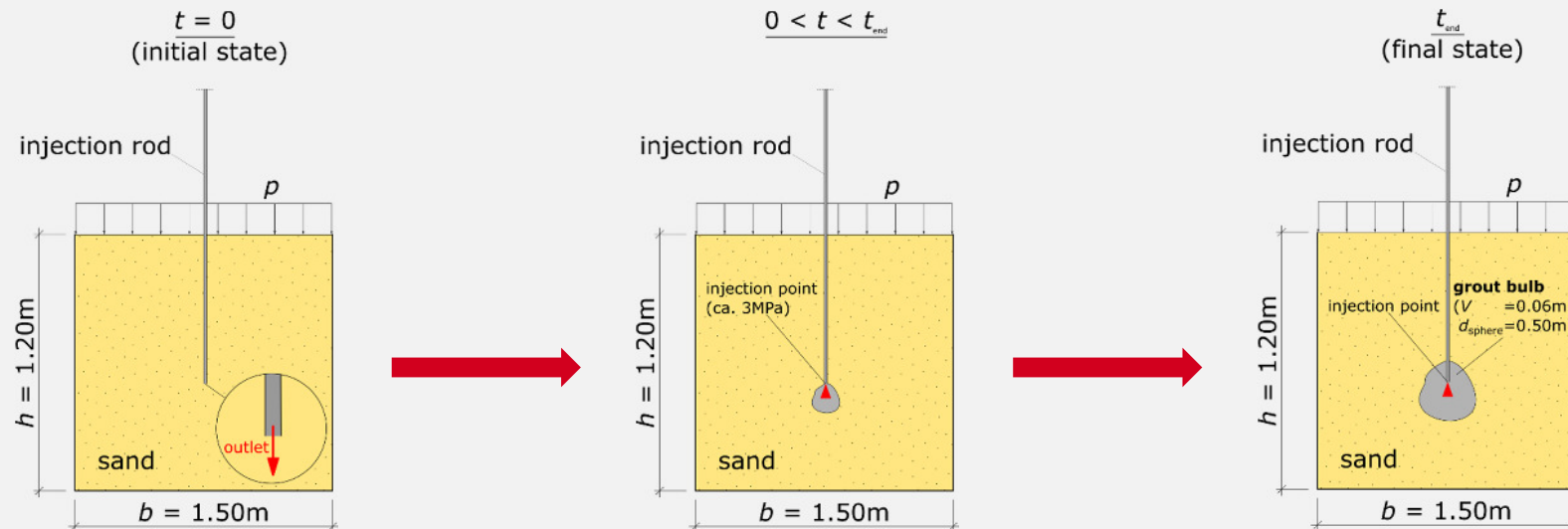


## Challenges

- “free growth” of the grout bulb
- large deformations (mesh distortion)
- proper constitutive laws
- **geometric and material nonlinearity**

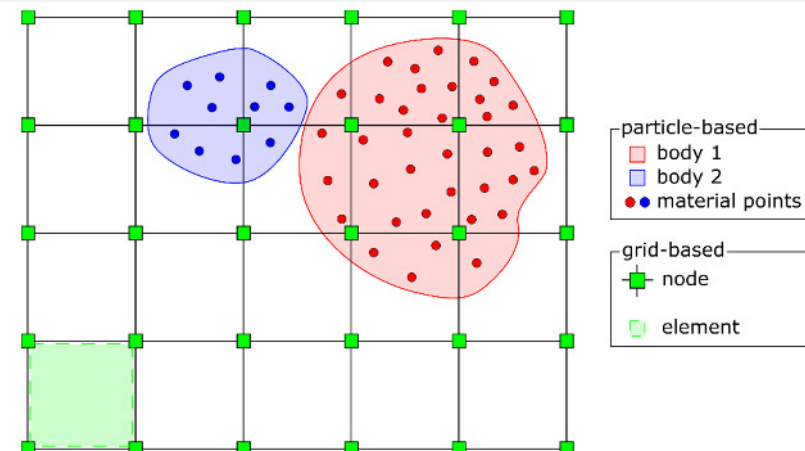


## Experimental setup (water saturated sand, drained condition)



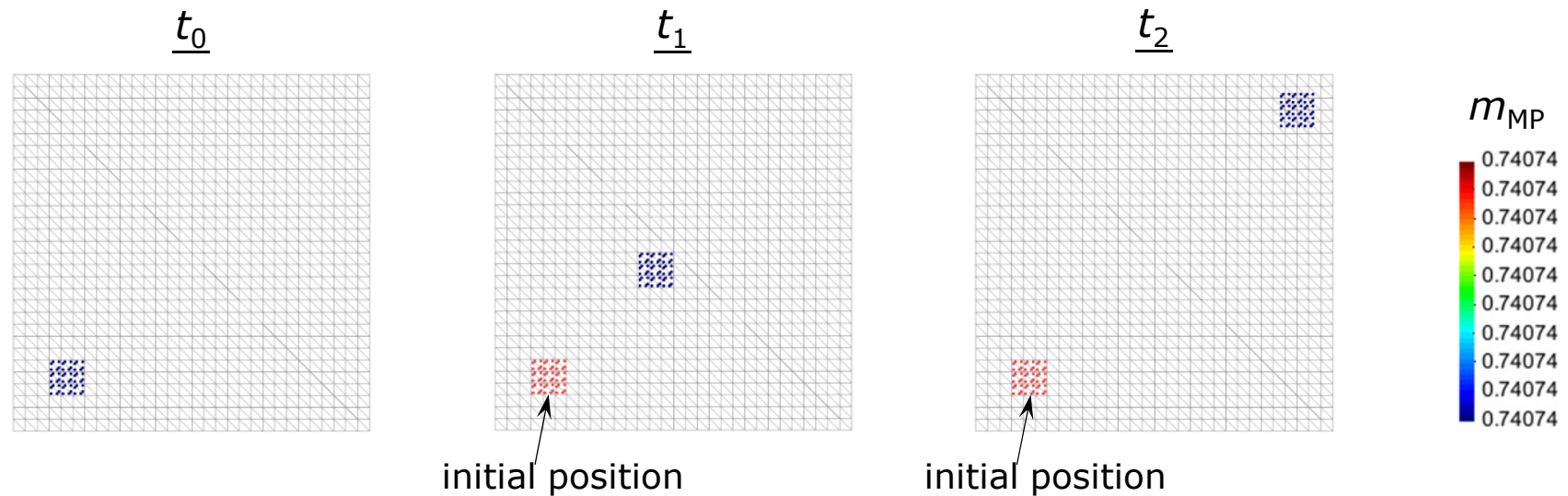
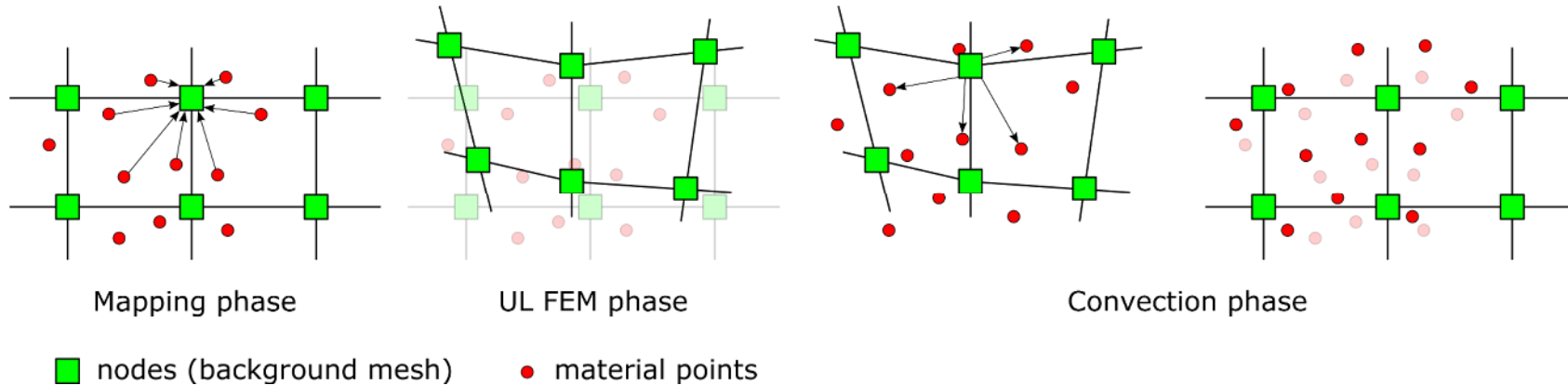
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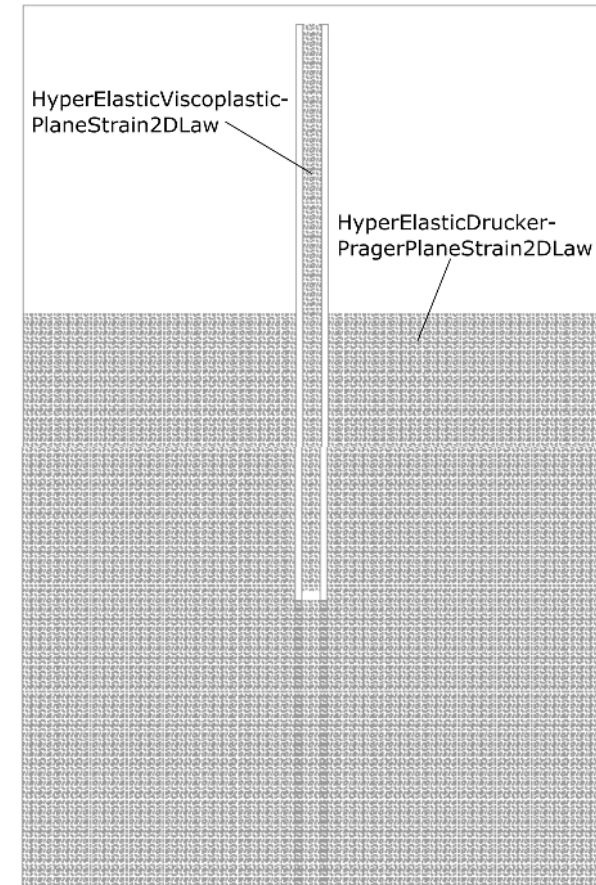
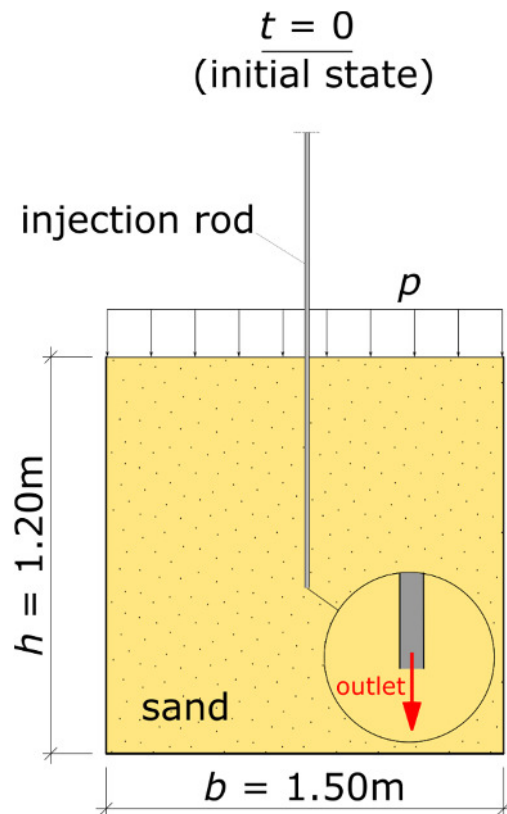


# Numerical simulation – Material Point Method (MPM)

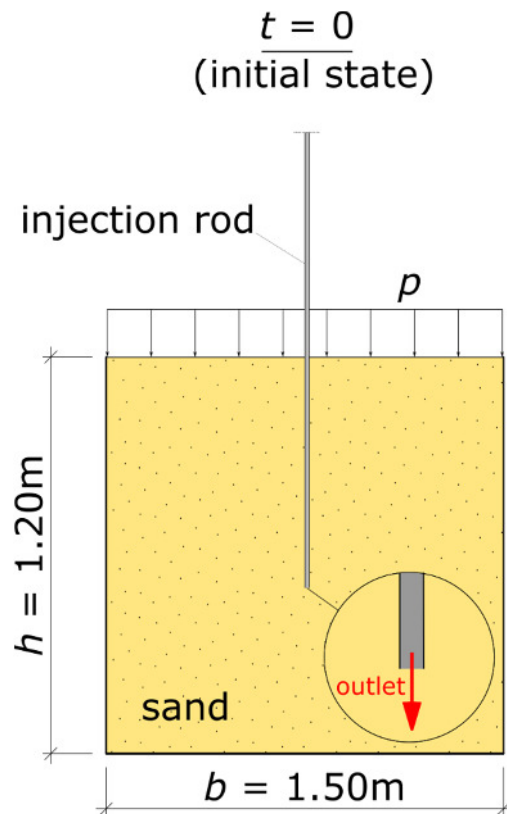




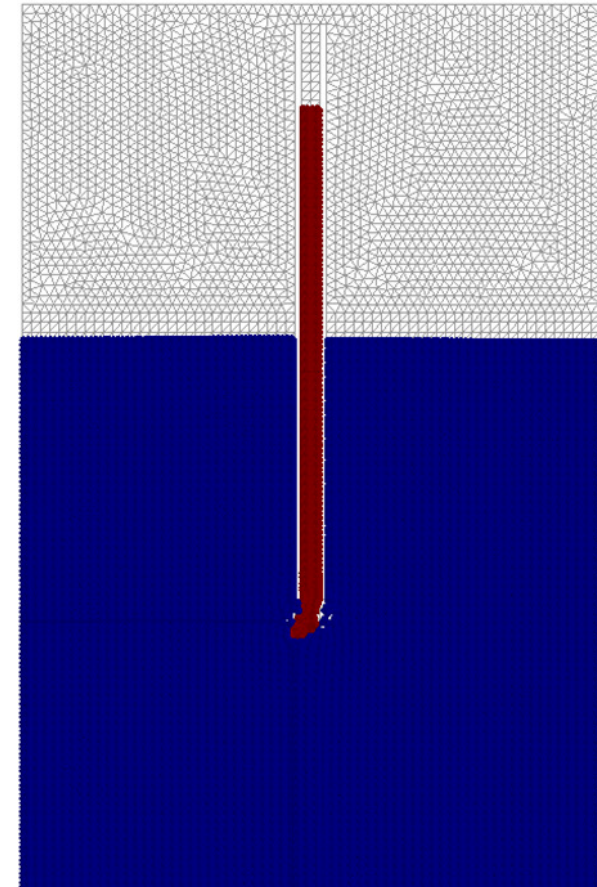
# MPM (DOF: $u$ formulation)



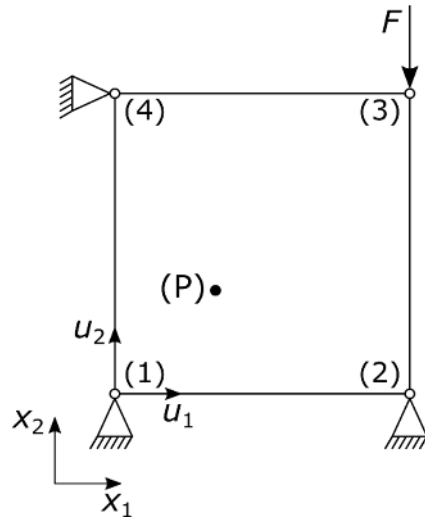
# MPM (DOF: $u$ formulation)



**Problem:**  
only applicable to  
low soil stiffness



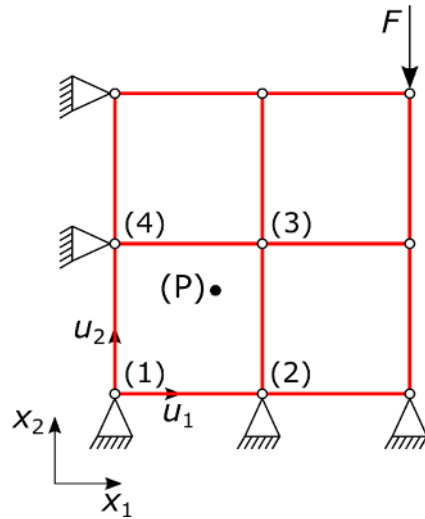
# MPM (DOF: $u$ formulation)



$$\begin{aligned}\varepsilon_V = 0 &= \text{tr}(\boldsymbol{\varepsilon}) = \varepsilon_{11} + \varepsilon_{22} + \varepsilon_{33} \\ &= \frac{du_1}{dx_1} + \frac{du_2}{dx_2} \quad (2D)\end{aligned}$$

$\rightarrow \underline{\underline{u_{(3)} = 0}} \rightarrow \text{element locks (zero displacement field)}$

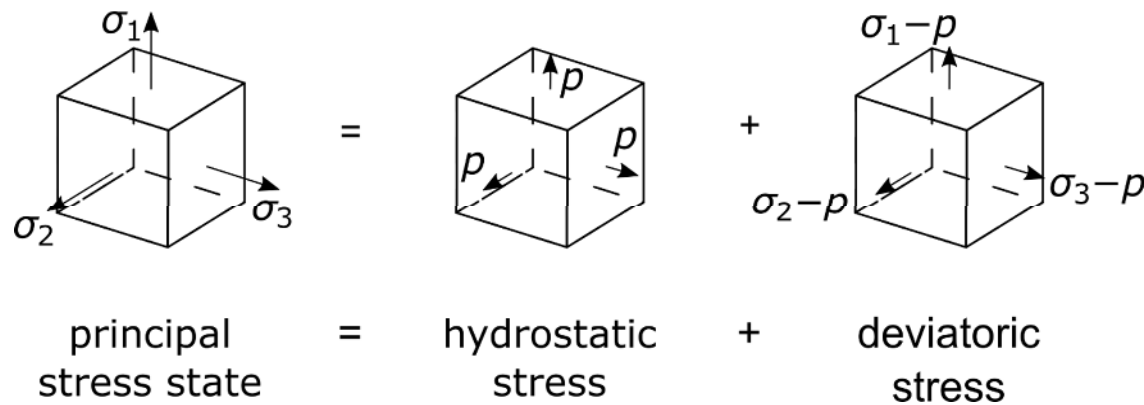
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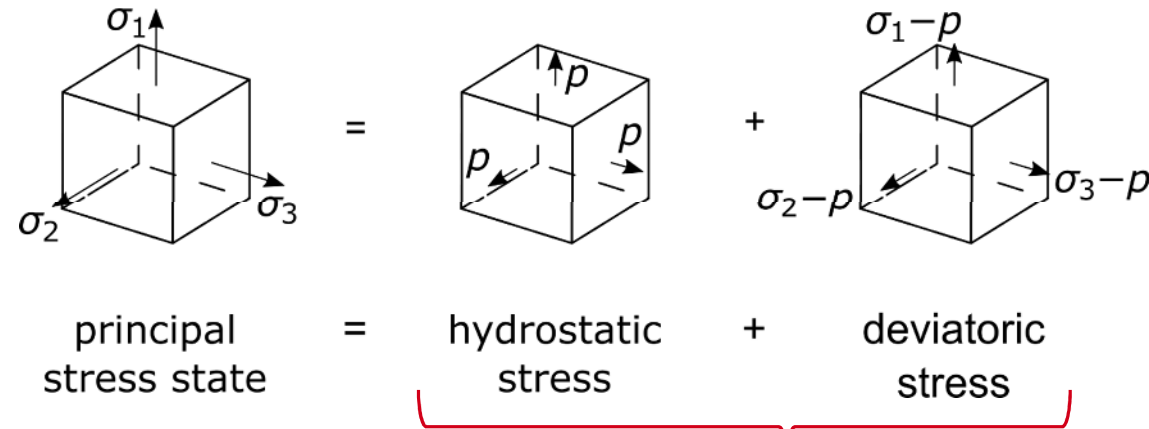
$$\varepsilon_V = 0 = \text{tr}(\boldsymbol{\varepsilon}) = \varepsilon_{11} + \varepsilon_{22} + \varepsilon_{33}$$

$$= \frac{du_1}{dx_1} + \frac{du_2}{dx_2} \quad (2D)$$

$\rightarrow \underline{\underline{u_{(3)} = 0}} \rightarrow$  element locks (zero displacement field)



# MPM (DOF: $u$ - $p$ formulation)



$$g_{\text{mom}} = \int_{\varphi(B)} \delta \underline{u} \cdot \underline{\ddot{u}} \cdot \rho_c dv + \int_{\varphi(B)} \delta \underline{\varepsilon} : \underbrace{(\underline{p} \cdot \underline{I} + \underline{\sigma}_{\text{dev}})}_{\underline{\sigma}} dv = \delta W_{\text{ext}}$$

$$r_{\text{press}} = \int_{\varphi(B)} \left( \underbrace{\underline{I} : \underline{\varepsilon}}_{\varepsilon_V} - p/K \right) dv = 0$$

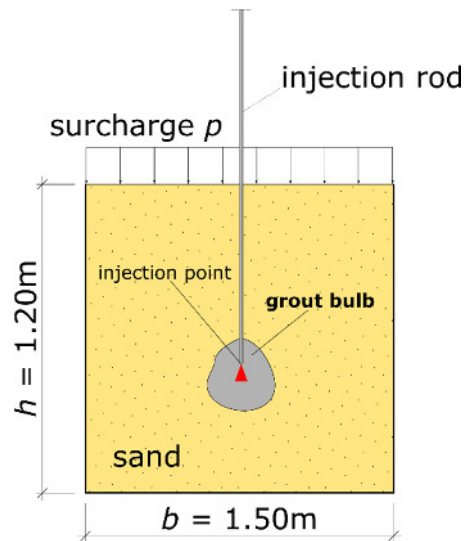
$$\mathbf{k}_T \cdot \underline{u}_{\text{DOF}} = \begin{pmatrix} D_u[g_{\text{mom}}(\overline{\varphi})] & D_p[g_{\text{mom}}(\overline{\varphi})] \\ D_u[r_{\text{press}}(\overline{\varphi})] & D_p[r_{\text{press}}(\overline{\varphi})] \end{pmatrix} \cdot \begin{pmatrix} \Delta \underline{u} \\ \Delta \underline{p} \end{pmatrix} = \begin{pmatrix} \underline{f}_{\text{ext}} \\ \underline{0} \end{pmatrix}$$

→ stabilisation necessary

(e.g. direct pressure stabilisation by Dohrmann & Bochev)

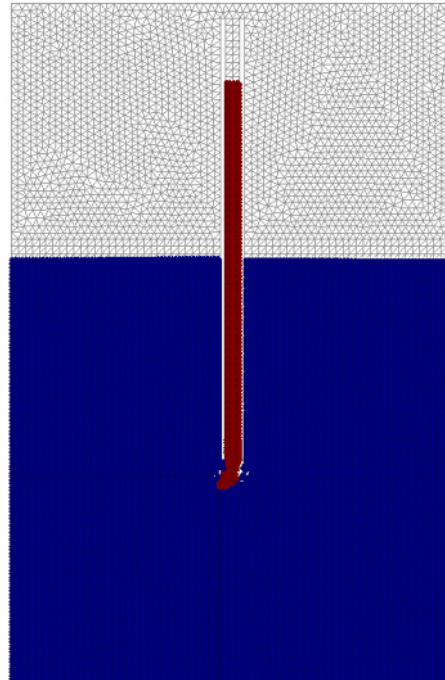
# MPM (DOF: $u$ - $p$ formulation)

## idea



## DOF: $u$ formulation

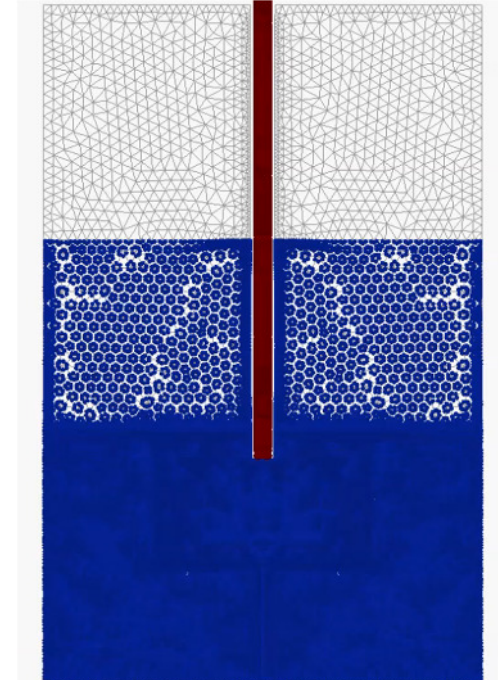
( $E_{\text{soil}} = 1\text{e}+5 \text{ N/m}^2$ )



**Problem:**  
only applicable to  
low soil stiffness

## DOF: $u$ - $p$ formulation

( $E_{\text{soil}} = 1\text{e}+7 \text{ N/m}^2$ )

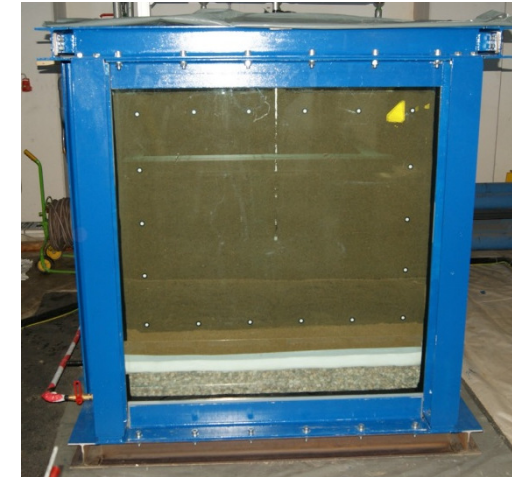
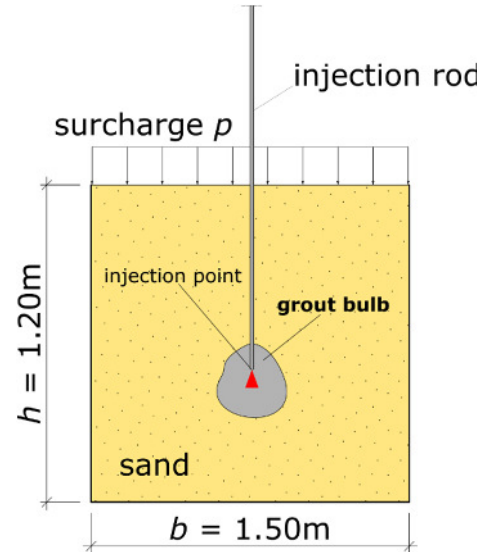
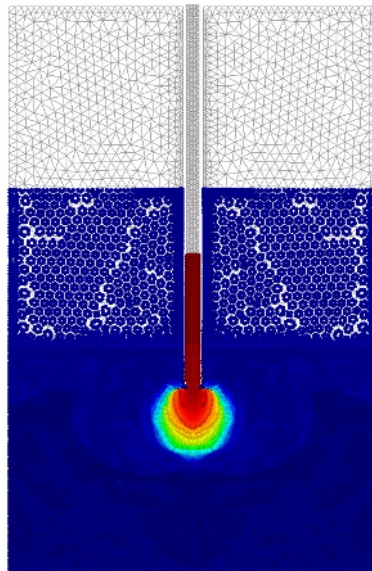


## Next steps:

- constitutive models
- rotational symmetry
- validation



# Challenges



## Numerical simulation

Numerical method

- large deformations
- constitutive models

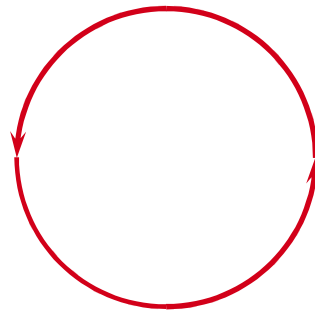
Software

- open source
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## Experiments

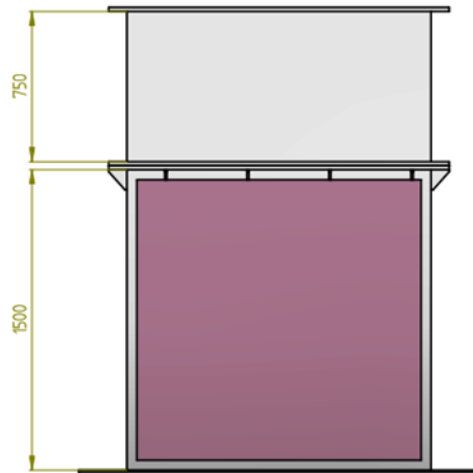
General concept

- setup
  - procedure
- Measurement methods
- Digital image processing (Aramis)



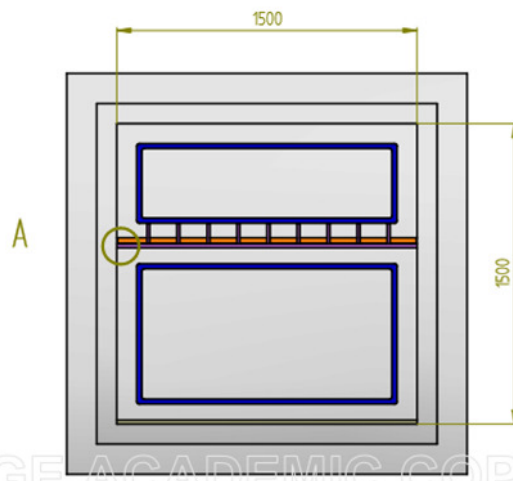


# Test container – Setup



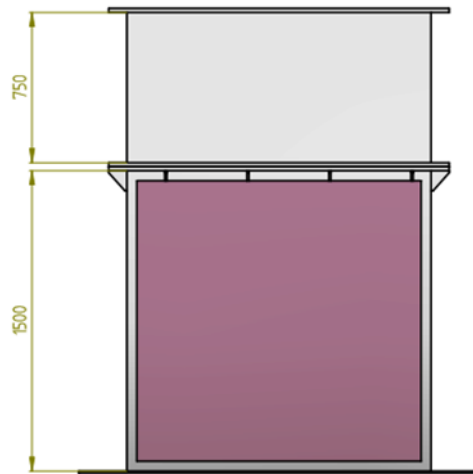
## Basic characteristics

- $b \times h \times t$ : 1.50m x 1.50m (+0.75m) x 1.50m
- glass pane: 110mm thick
- surcharge  $p$ : 160kN/m<sup>2</sup>
- drainage: one-sided on the bottom
- injection rod: two locations



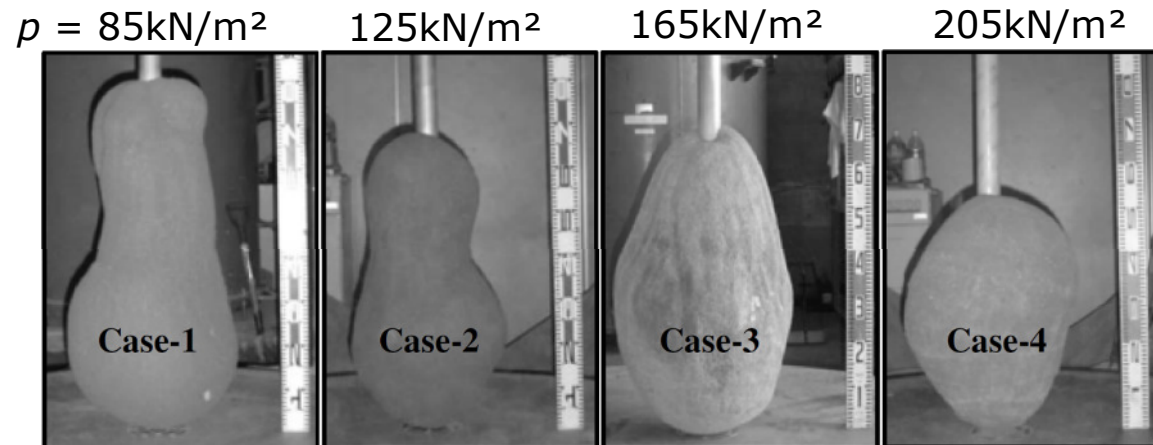
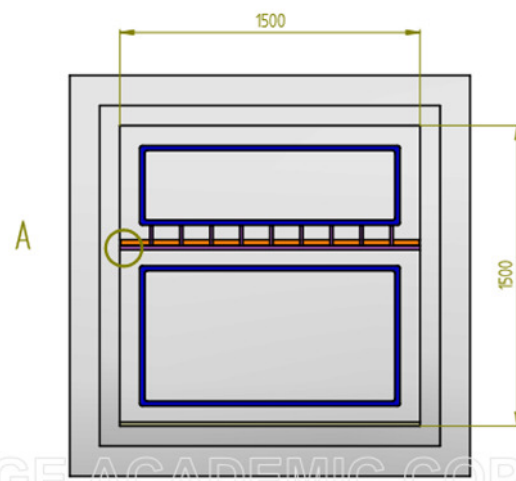
(Compaction Grouting Consensus Guide, 2007)

# Test container – Setup



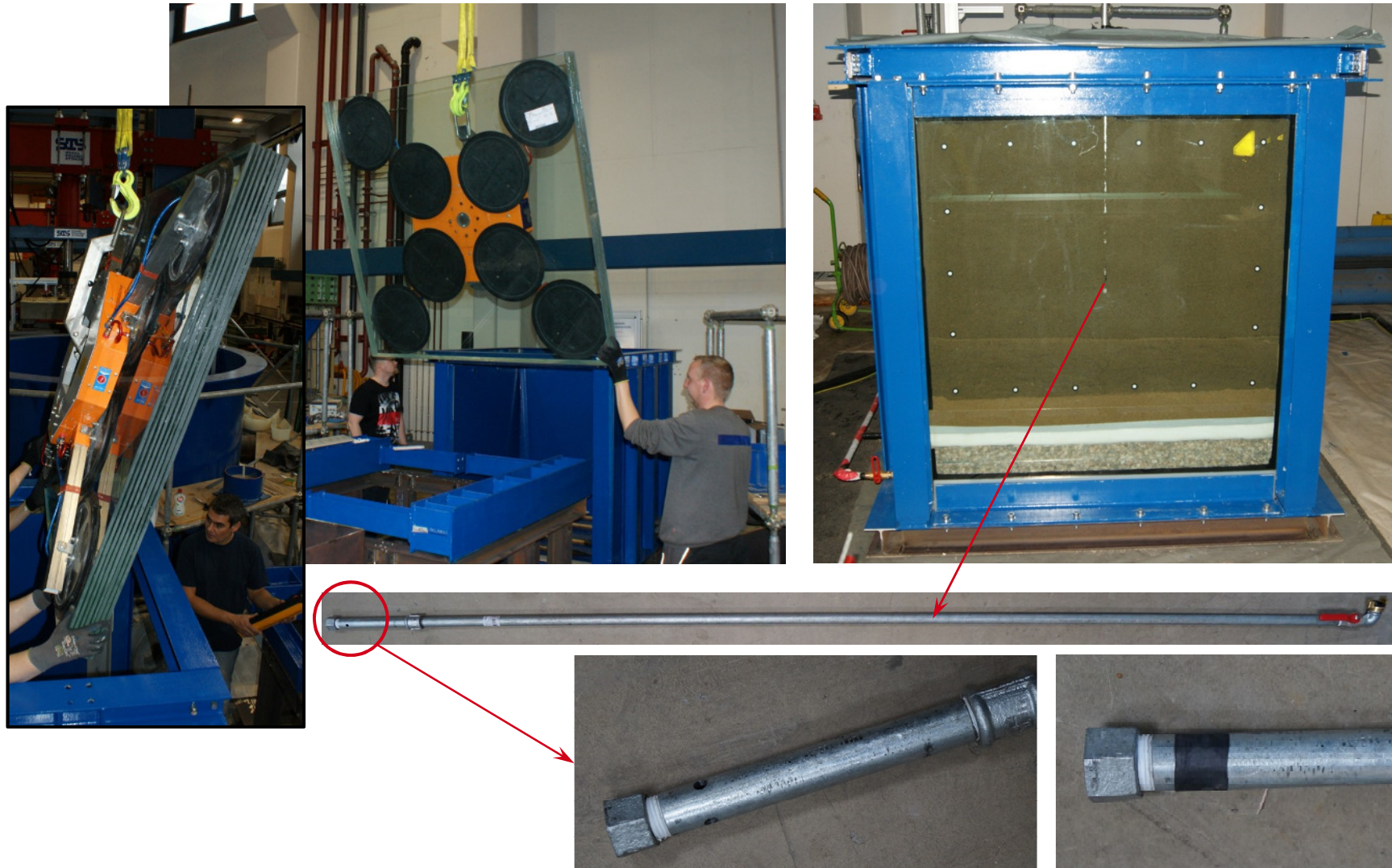
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(El-Kelesh et al., 2007)

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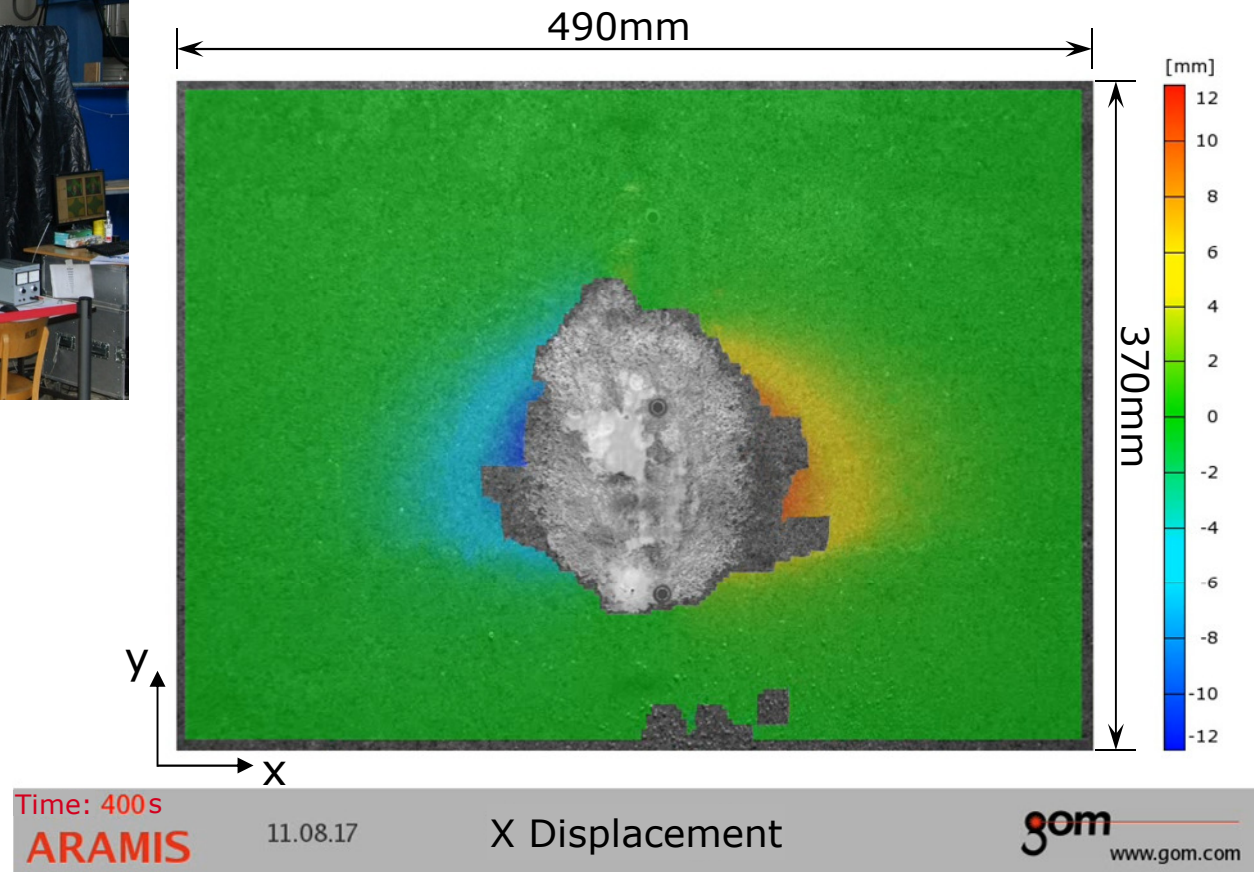




# Test container – Digital Image Processing

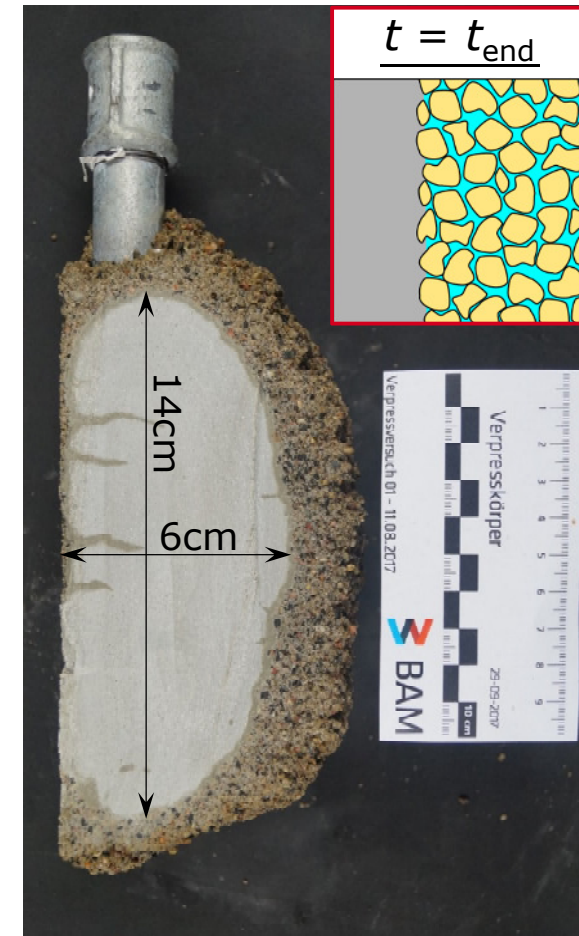


# Test container – Digital Image Processing





# Test container – Grout bulb



# Conclusion – Compaction Grouting

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## Definition (DIN EN 12715, October 2000)

“A displacement grouting method which aims at forcing a mortar of high internal friction into the soil to compact it without fracturing it.”

## Applications

- retrofitting, stabilisation, settlement control

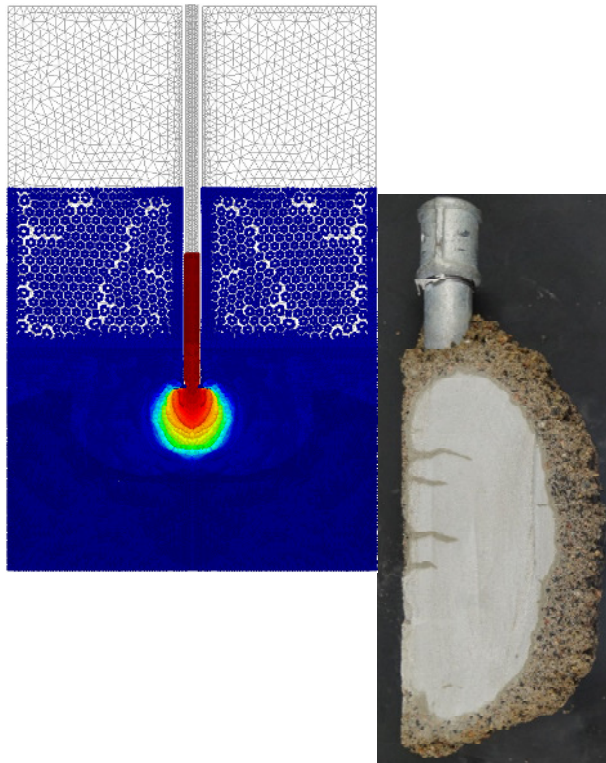
## Numerical simulations

- large deformation (Material Point Method)
- incompressibility ( $u$ - $p$  formulation)
- nonlinear behaviour of soil and grout (proper constitutive models)

## Experiments

- lab tests (variation of parameters (e.g. surcharge, relative density of sand))
- large-scale tests on pile foundations





**Thank you for  
listening.**